



# Parameter Estimation in EnKF: Surface Fluxes of Carbon, Heat, Moisture and Momentum

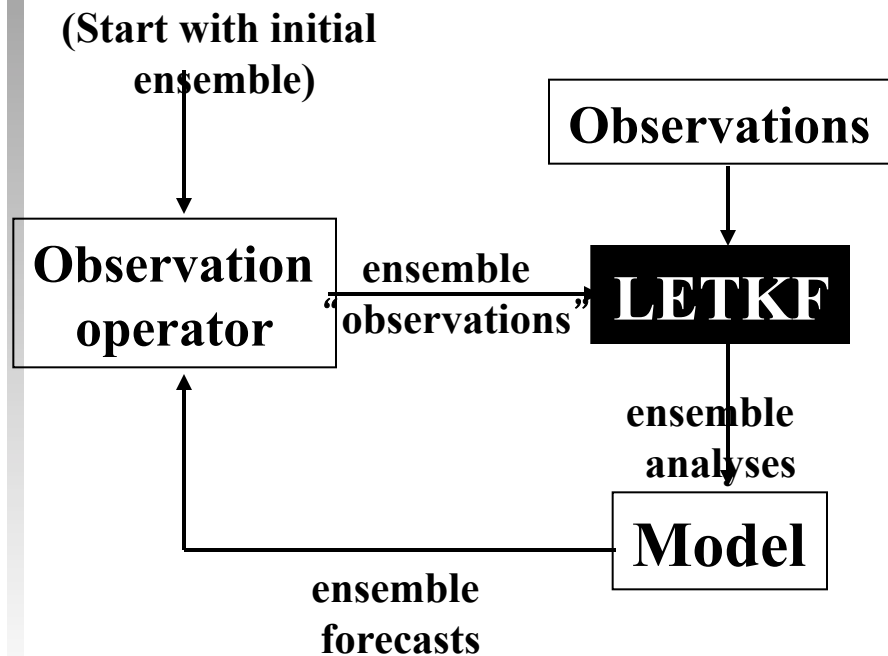
**Ji-Sun Kang**, **Eugenia Kalnay**, Takemasa Miyoshi,  
Junjie Liu, Inez Fung, Kayo Ide and many collaborators  
at the University of Maryland **Weather-Chaos** group

# Outline

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- Review of a few **recent advances** in LETKF
    - Running in Place
    - Effective assimilation of precipitation
    - Ensemble Forecast Sensitivity to Observations (EFSO)
  - **Parameter estimation** in LETKF
  - **Carbon cycle** data assimilation: **LETKF-C**
  - Estimation of **surface heat and moisture fluxes**
    - Sensible and latent heat fluxes (SHF, LHF)
  - Estimation of **wind stress** in addition to SHF and LHF
  - Future Plans
-

# 4D-Local Ensemble Transform Kalman Filter (Ott et al, 2004, Hunt et al, 2004, 2007)

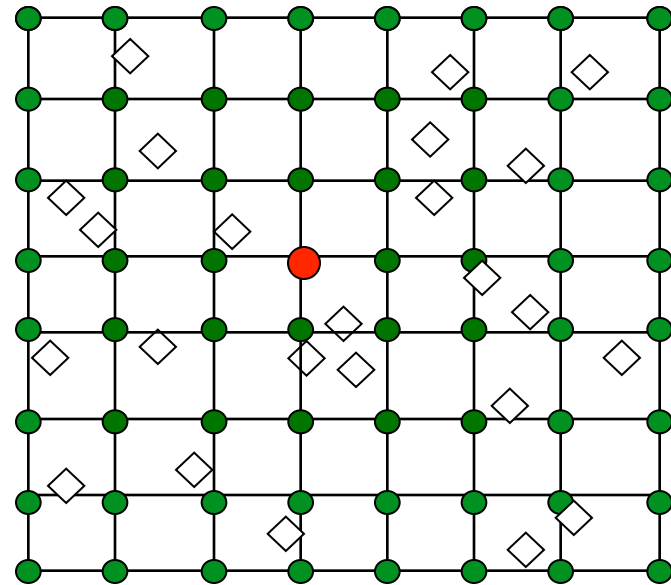


- Model independent (black box)
- **Obs. assimilated simultaneously at each grid point**
- **100% parallel**
- No **adjoint** needed
- 4D LETKF extension
- **Computes the weights for the ensemble forecasts explicitly**

# Localization based on observations

Perform data assimilation in a local volume, choosing observations

The state estimate is updated at the central grid **red** dot

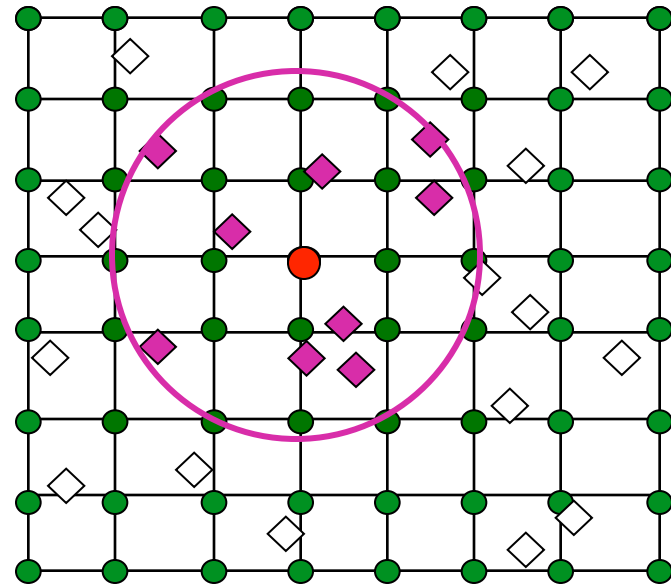


# Localization based on observations

Perform data assimilation in a local volume, choosing observations

The state estimate is updated at the central grid **red** dot

All observations (**purple diamonds**) within the local region are assimilated



The LETKF algorithm can be described **in a single slide!**

# Local Ensemble Transform Kalman Filter (LETKF)

## Globally:

Forecast step:

$$\mathbf{x}_{n,k}^b = M_n \left( \mathbf{x}_{n-1,k}^a \right)$$

Analysis step: construct

$$\mathbf{X}^b = \left[ \mathbf{x}_1^b - \bar{\mathbf{x}}^b \mid \dots \mid \mathbf{x}_K^b - \bar{\mathbf{x}}^b \right];$$

$$\mathbf{y}_i^b = H(\mathbf{x}_i^b); \mathbf{Y}_n^b = \left[ \mathbf{y}_1^b - \bar{\mathbf{y}}^b \mid \dots \mid \mathbf{y}_K^b - \bar{\mathbf{y}}^b \right]$$

**Locally:** Choose for **each grid point** the observations to be used, and compute the local analysis error covariance and perturbations in **ensemble space**:

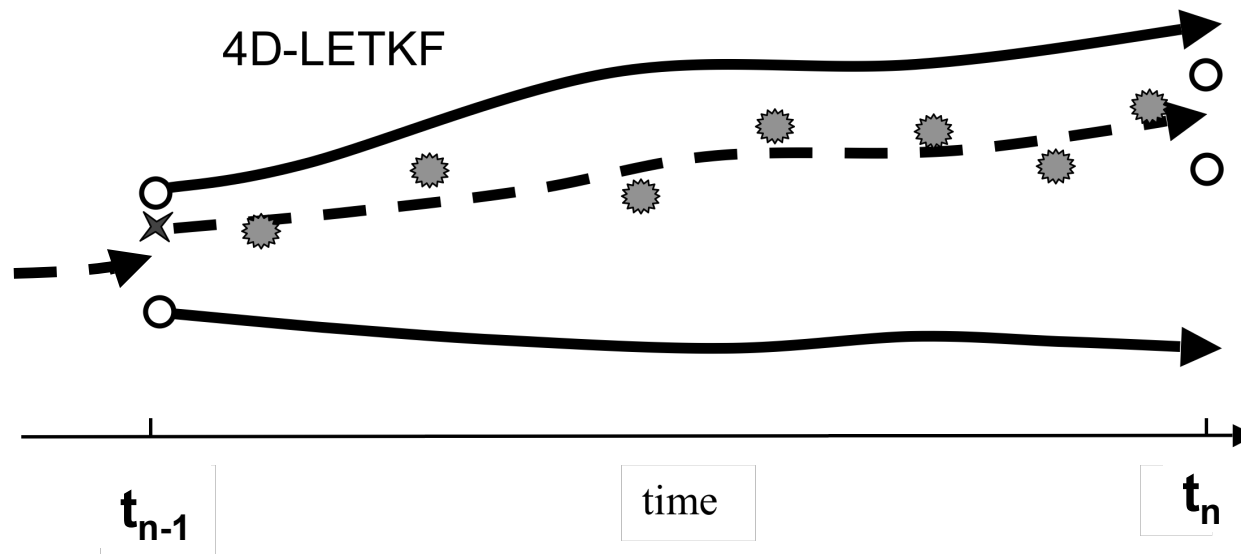
$$\tilde{\mathbf{P}}^a = \left[ (K-1)\mathbf{I} + \mathbf{Y}^T \mathbf{R}^{-1} \mathbf{Y} \right]^{-1}; \mathbf{W}^a = \left[ (K-1)\tilde{\mathbf{P}}^a \right]^{1/2}$$

Analysis mean in ensemble space:  $\bar{\mathbf{w}}^a = \tilde{\mathbf{P}}^a \mathbf{Y}^{bT} \mathbf{R}^{-1} (\mathbf{y}^o - \bar{\mathbf{y}}^b)$

and add to  $\mathbf{W}^a$  to get **the analysis ensemble in ensemble space**.

The new ensemble analyses in **model space** are the columns of  $\mathbf{X}_n^a = \mathbf{X}_n^b \mathbf{W}^a + \bar{\mathbf{x}}^b$ . Gathering the grid point analyses forms the new **global analyses**. Note that the the output of the LETKF are analysis weights  $\bar{\mathbf{w}}^a$  and perturbation analysis matrices of weights  $\mathbf{W}^a$ . **These weights multiply the ensemble forecasts.**

**No-cost LETKF smoother (✕): apply at  $t_{n-1}$  the same weights found optimal at  $t_n$ . It works for 3D- or 4D-LETKF**



The no-cost smoother makes possible:

- ✓ Quasi Outer Loop (QOL)
- ✓ “Running in place” (RIP) for faster spin-up
- ✓ Use of future data in reanalysis
- ✓ Ability to use longer windows and nonlinear perturbations

# Promising new tools for the LETKF (1)

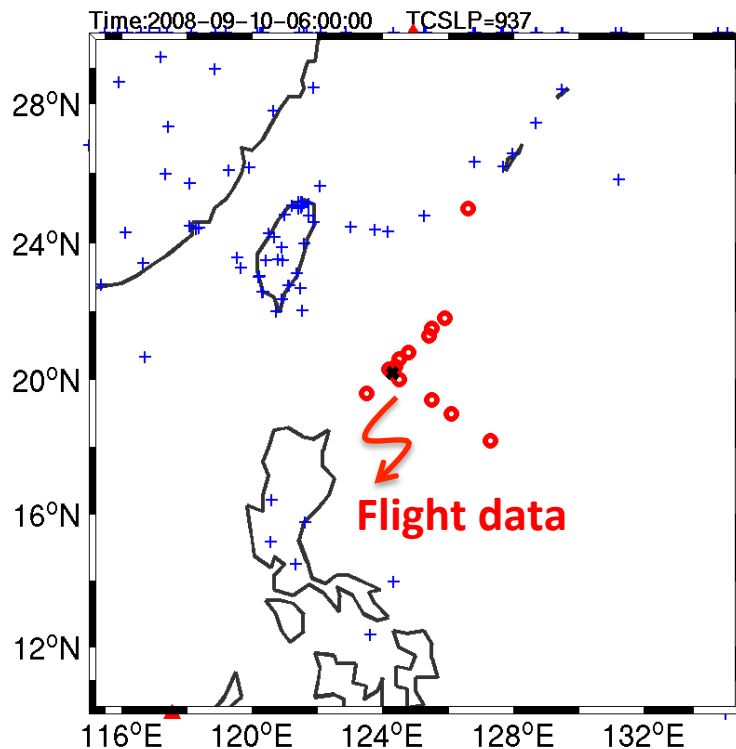
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**1. Running in Place** (Kalnay and Yang, QJ 2010, Yang, Kalnay, and Hunt, MWR, 2012)

- It extracts more information from observations by **using them more than once** (considered a sin by many!).
- Useful during spin-up (e.g., hurricanes and tornados).
- It uses the “no-cost smoother”, Kalnay et al., Tellus, 2007b.
- Typhoon Sinlaku (Yang et al., 2012)
- 7-years of Ocean Reanalysis (Penny, 2011, Penny et al., 2012)



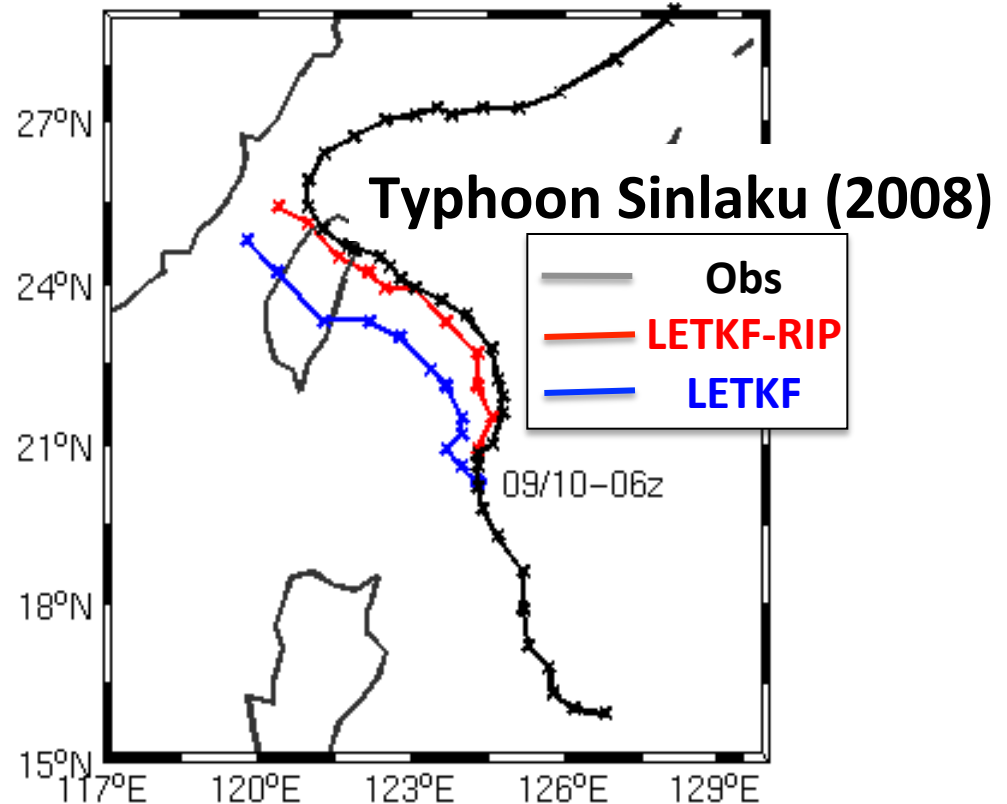
# LETKF-RIP with real observations (Typhoon Sinlaku, 2008)



SYNOP(+), SOUND( $\Delta$ ),  
DROPSONDE(o),

Typhoon center (X)

3-day forecast



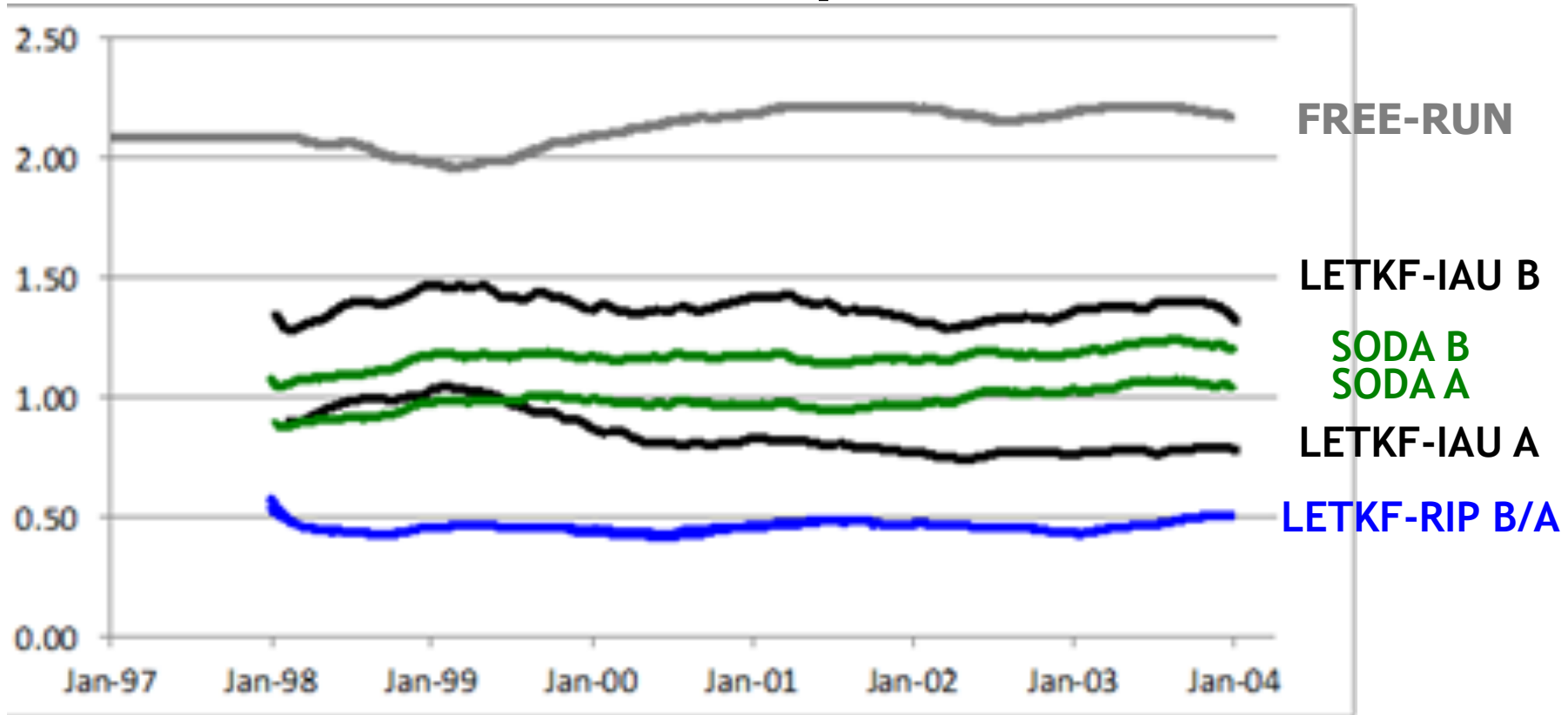
RIP uses better the “limited observations”!

Courtesy of Prof. Shu-Chih Yang (NCU, Taiwan)

RMSD ( $^{\circ}\text{C}$ ) (All vertical levels)

# 7 years of Ocean Reanalysis Temperature

B: background  
A: analysis



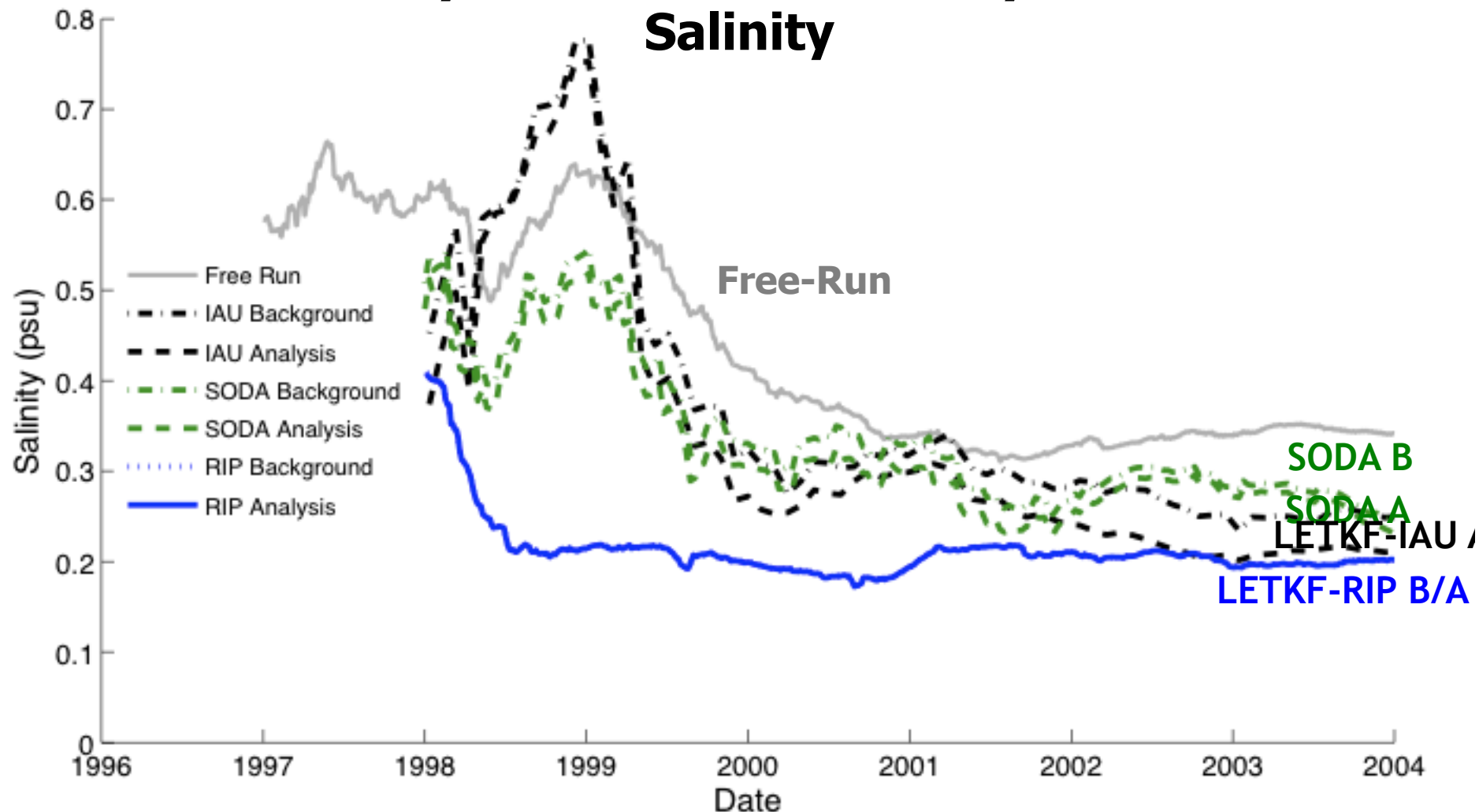
Global RMS(O-F) of Temperature ( $^{\circ}\text{C}$ ),  
12-month moving average

LETKF (with IAU), SODA and LETKF with RIP

RMSD (psu) (All vertical levels)

B: background  
A: analysis

# 7 years of Ocean Reanalysis Salinity



Global RMS(O-F) of Salinity (psu),  
12-month moving average

LETKF (with IAU), **SODA** and LETKF with **RIP**

# Promising new tools for the LETKF (2)

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## 2. Effective assimilation of Precipitation (Guo-Yuan Lien, Eugenia Kalnay and Takemasa Miyoshi, 2013)

- Assimilation of precipitation has generally failed to improve forecasts beyond a day.
- A new approach deals with non-Gaussianity, and assimilation of both zero and non-zero precipitation.
- Rather than changing moisture to force the model to rain as observed, the LETKF changes the potential vorticity.
- The model now “remembers” the assimilation, so that that medium range forecasts are improved.

# How do we transform precipitation $y$ to a Gaussian $y_{transf}$ ?

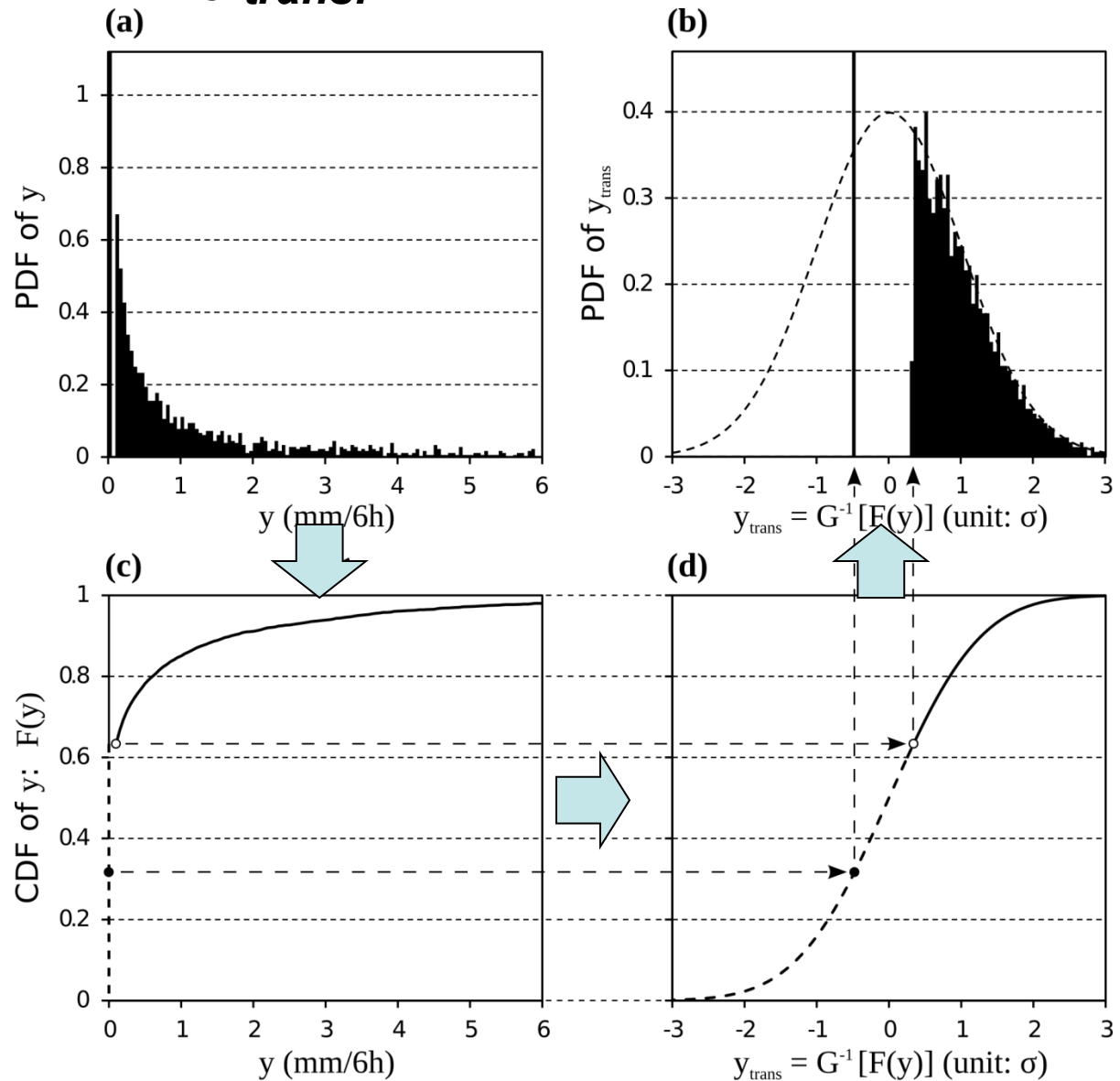
Start with pdf of  $y$ =rain at every grid point.

“No rain” is like a delta function that we cannot transform.

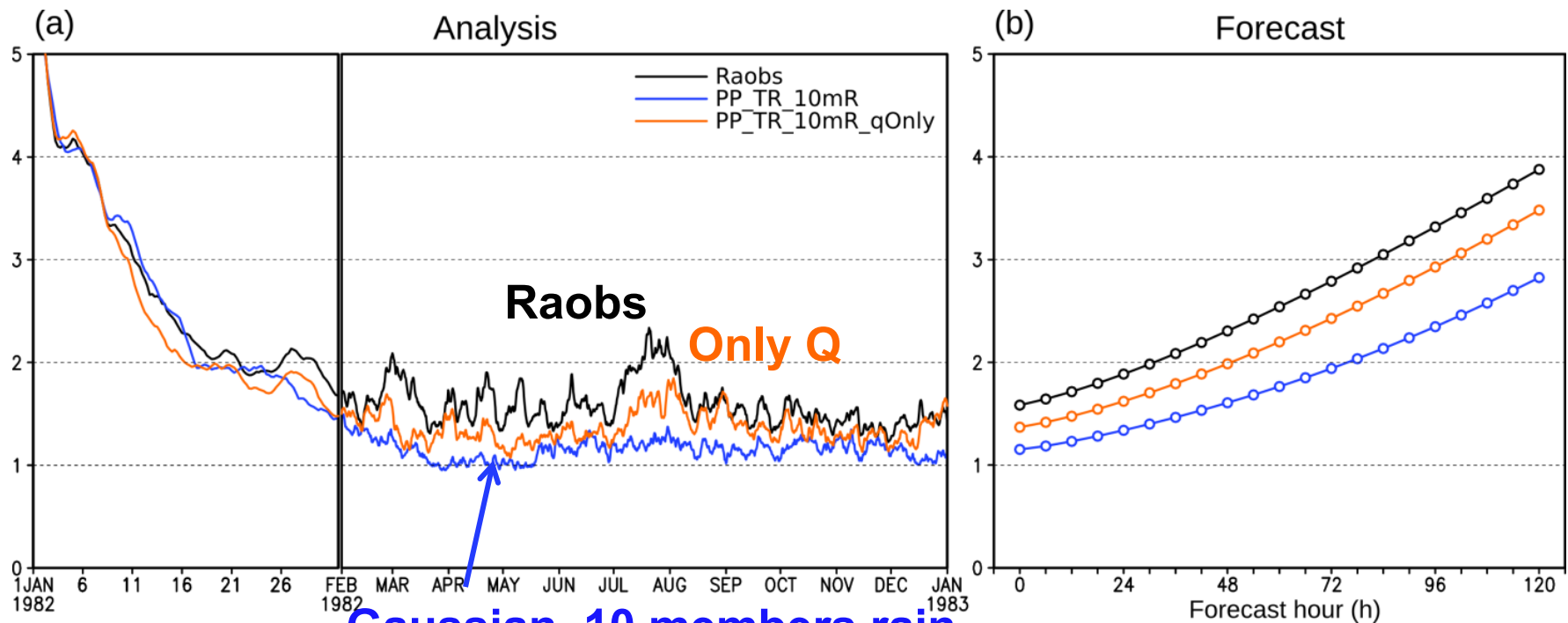
We assign all “no rain” to the median of the no rain CDF.

We found this works as well as more complicated procedures.

It allows to assimilate both rain and no rain.



$$G^{-1}(x) = \sqrt{2} \operatorname{erf}^{-1}(2x - 1)$$



**Gaussian, 10 members rain,  
20% error, all variables**

- **Main result:** with at least 10 ensemble members raining in order to assimilate an obs, updating all variables (including vorticity), with Gaussian transform, and rather accurate observations (20% errors), **the analyses and forecasts are much improved!**
- **Updating only Q is much less effective.**
- **The 5-day forecasts maintain the advantage!**

# Promising new tools for the LETKF (3)

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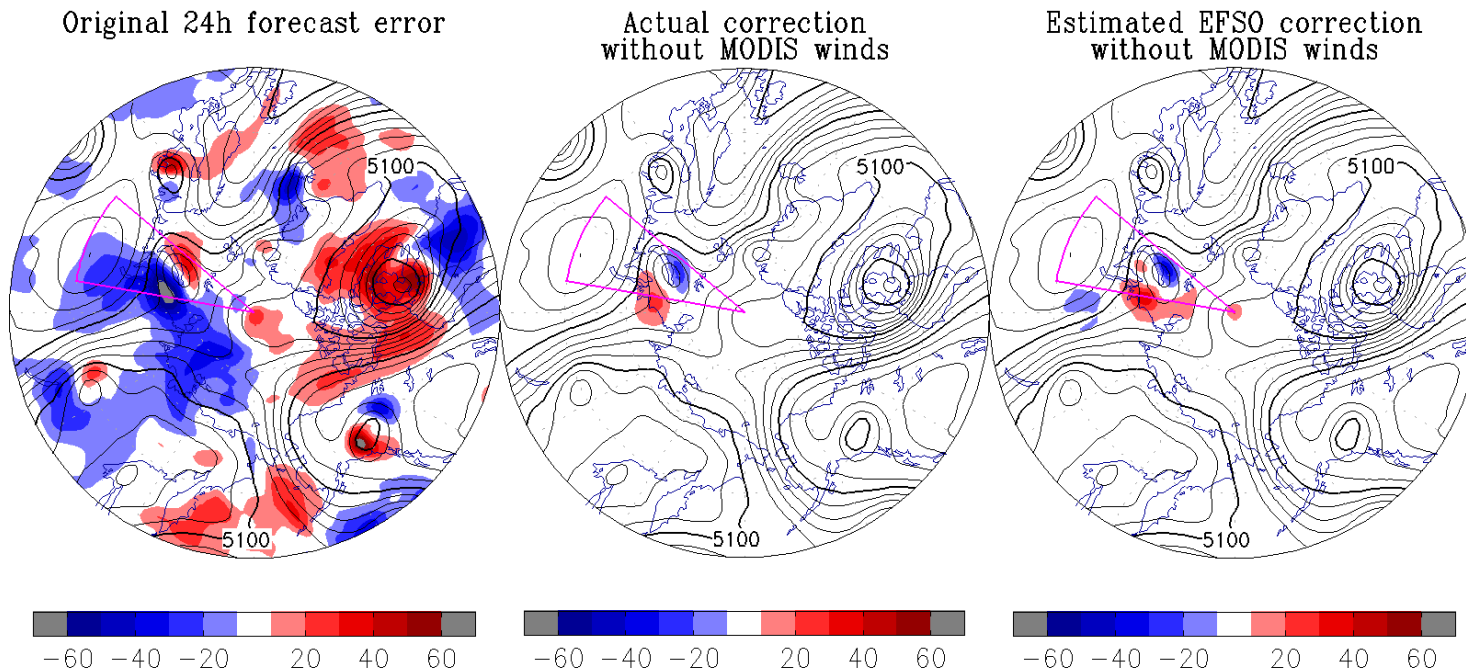
## 3. Forecast Sensitivity to Observations and proactive QC”

(with Y Ota, T Miyoshi, J Liu, and J Derber)

- A simpler, more accurate formulation for the Ensemble Forecast Sensitivity to Observations (EFSO, Kalnay et al., 2012, Tellus).
- Ota et al., 2013 tested it with the NCEP EnSRF-GFS operational system using all operational observations.
- Allows to identify “bad observations” after 12 or 24hr, and then repeat the data assimilation without them: “**proactive QC**”.

# “Proactive QC”:

Bad observations can be identified by EFSO and withdrawn from the data assimilation



**After identifying MODIS polar winds producing bad 24 hr regional forecasts, the withdrawal of these winds reduced the forecast errors by 39%, as projected by EFSO.**



# Promising new tools for the LETKF (4)

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## 4. Estimation of surface fluxes as evolving parameters

(Kang et al., 2011, Kang et al., 2012)

- Important for the carbon cycle
- surface fluxes of heat, moisture, and momentum
- eventually for coupled data assimilation

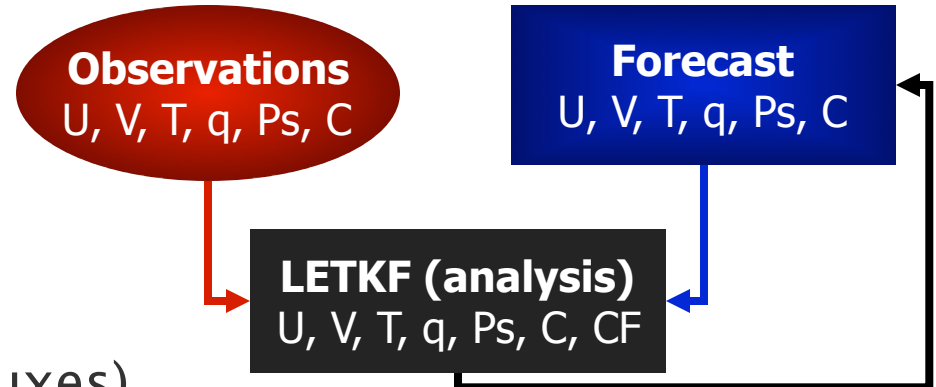
**This is the rest of the talk (Ji-Sun Kang  
with E. Kalnay, J. Liu and Inez Fung)**

# Parameter estimation in EnKF

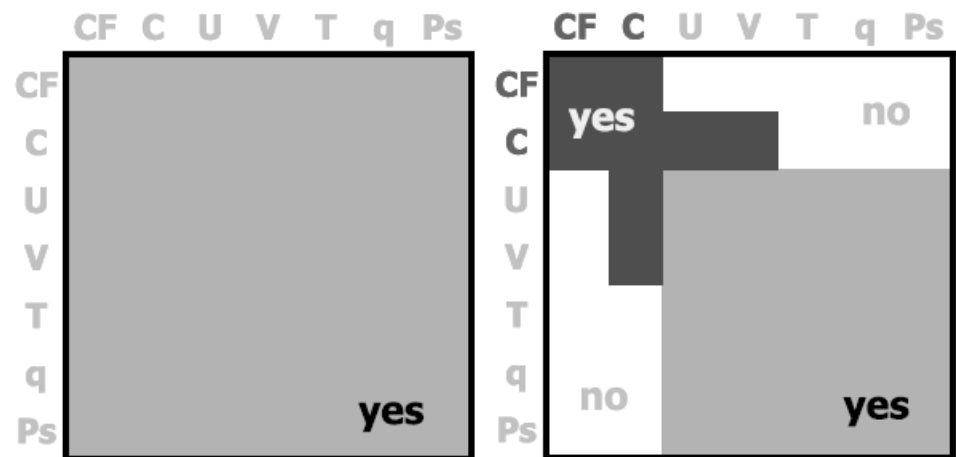
- State vector augmentation

$$\mathbf{X}^b = \begin{bmatrix} \mathbf{X} \\ \mathbf{CF} \end{bmatrix} \begin{array}{l} \text{: model state vector} \\ \text{(U, V, T, q, Ps, C)} \\ \text{: surface CO}_2 \text{ flux} \end{array}$$

- Append **CF** (surface CO<sub>2</sub> fluxes)
- Update **CF** as part of the data assimilation process
- Multivariate analysis with **a localization of the variables** (Kang et al., 2011)



Schematic plots of background error covariance matrix  $\mathbf{P}^b \rightarrow$  without "variable localization" (left) and with it (right)



# LETKF-C with SPEEDY-C

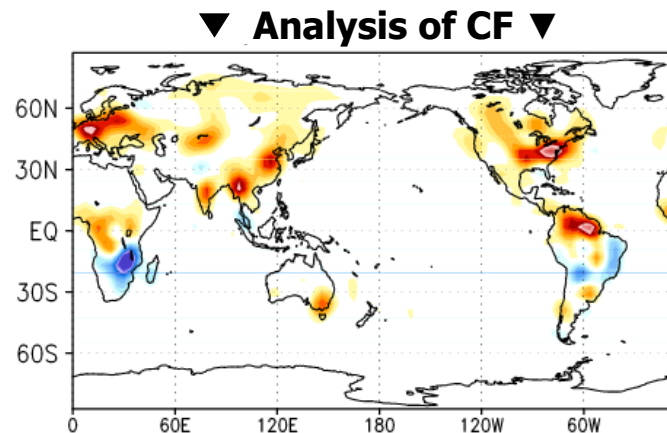
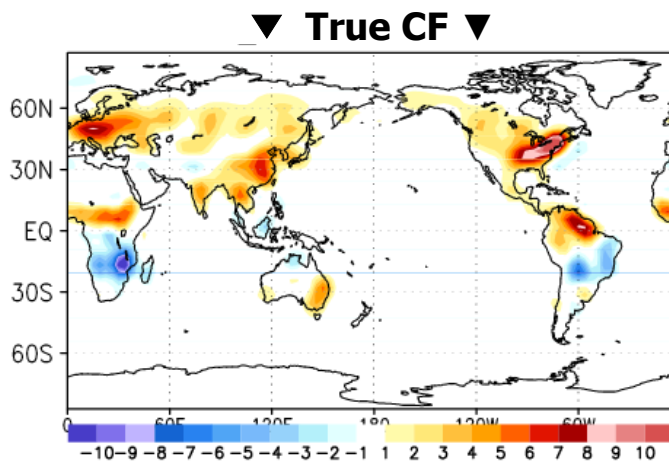
- Model: **SPEEDY-C** (Molteni, 2003; Kang, 2009)
  - Spectral AGCM model with T30L7
  - Prognostic variables: U, V, T, q, Ps, C
    - ✓ C (atmospheric CO<sub>2</sub>): an inert tracer
  - Persistence forecast of Carbon Fluxes (CF), no observations
- Simulated observations
  - Rawinsonde observations of U, V, T, q, Ps
  - Ground-based observations of atmospheric CO<sub>2</sub>
    - ✓ 18 hourly and 107 weekly data on the globe
  - Remote sensing data of column mixing CO<sub>2</sub>
    - ✓ **AIRS** whose averaging kernel peaks at mid-troposphere
    - ✓ **GOSAT** whose averaging kernel is nearly uniform throughout the column
- Initial condition: random (no *a-priori* information)
- 20 ensembles

# LETKF-C

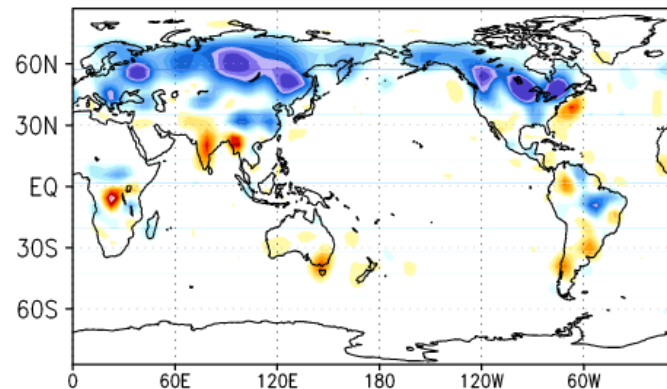
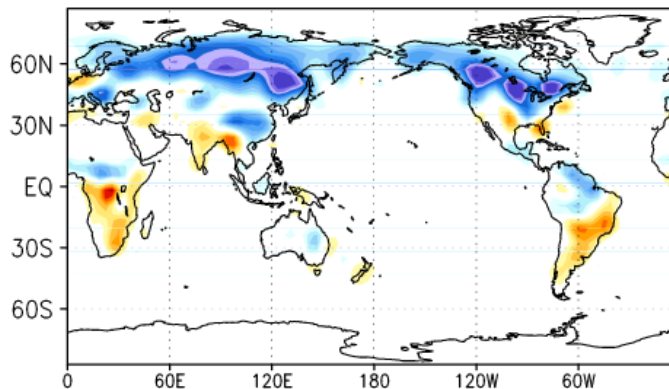
- Carbon cycle data assimilation within LETKF (Kang et al., JGR, 2011, 2012)
  - Simultaneous analysis of meteorological and carbon variables
  - “Localization of Variables” reduces sampling errors
  - Advanced inflation methods
  - Vertical localization of column mixing CO<sub>2</sub> observations
  - Short (6-hour) assimilation window
    - ✓ Many of CO<sub>2</sub> inversion groups adopt much **longer window lengths** (weeks ~ months)
      - Started in the 1980’s when there were only tens or hundreds of ground-based observations on the globe
      - CO<sub>2</sub> is an inert gas that stays long in the atmosphere so that the atmospheric CO<sub>2</sub> has quite long memory of CF.
      - ➔ ***We have satellite observations of CO<sub>2</sub>*** (e.g. AIRS, GOSAT, OCO-2)
      - ➔ ***The long memory can be useful only if we can keep track of CO<sub>2</sub> flow***

# Results

00Z01APR ▶  
After three months of DA

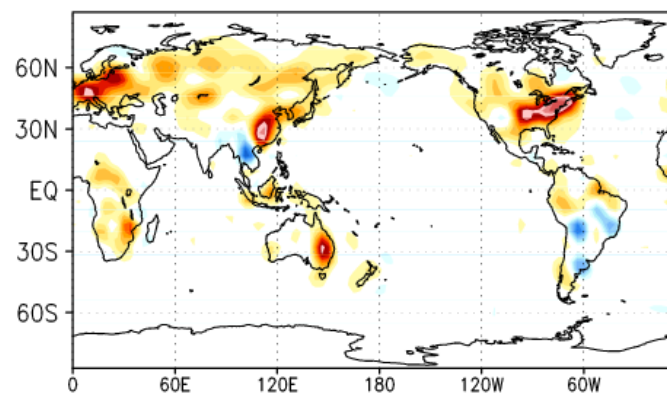
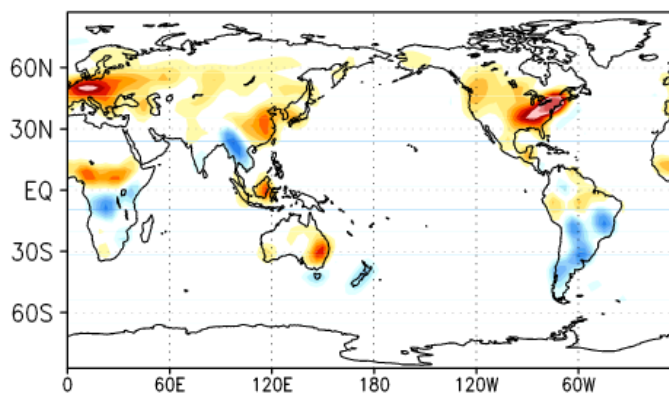


00Z01AUG ▶  
After seven months of DA

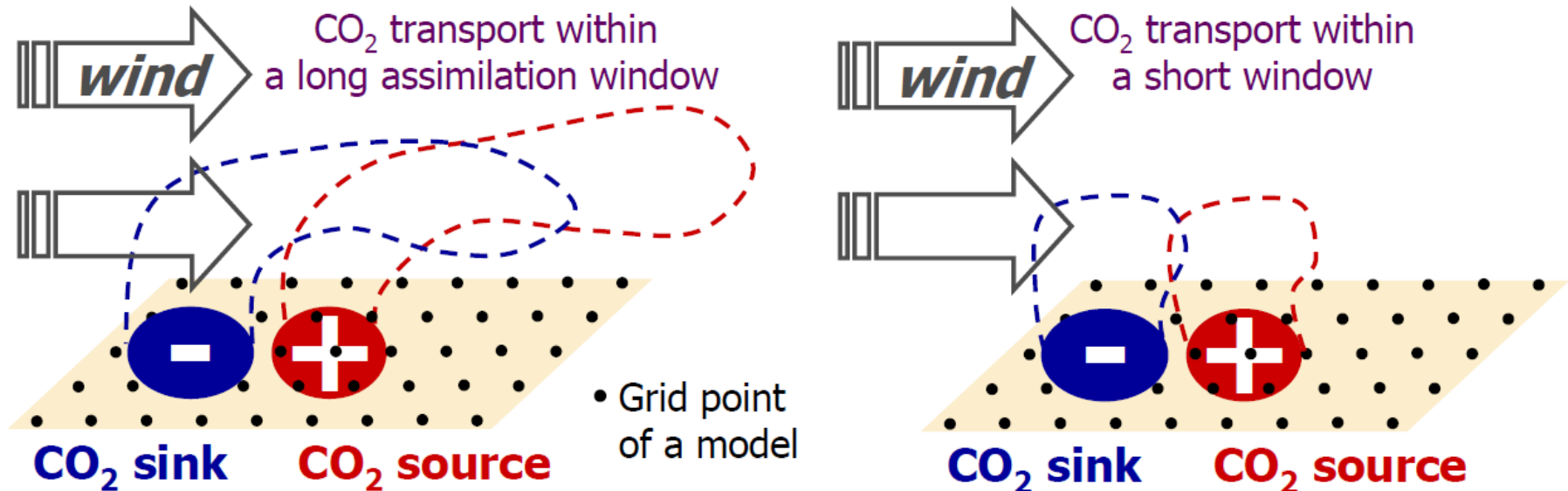


*We succeeded in estimating time-evolving CF at model-grid scale*

00Z01JAN ▶  
After one year of DA



# Assimilation window in LETKF-C



- CO<sub>2</sub> data assimilation system
  - A short assimilation window reduces the attenuation of observed CO<sub>2</sub> information because the analysis system can use the strong correlation between C and CF **before the transport of atmospheric CO<sub>2</sub> blurs out the essential information of surface CO<sub>2</sub> forcing**
  - We may not be able to reflect the optimal correlation between C and CF within a long assimilation window, which can introduce sampling errors into the EnKF analysis

# Long vs. short window in LETKF-C

- **OSSEs with SPEEDY-C**

- Realistic observation distributions for meteorological variables and CO<sub>2</sub>
  - ✓ Rawinsonde observation for (U, V, T, q, Ps)
  - ✓ Ground-based observations, AIRS and GOSAT CO<sub>2</sub> mixing ratio for C

- **Experiment1: Analysis from LETKF-C**

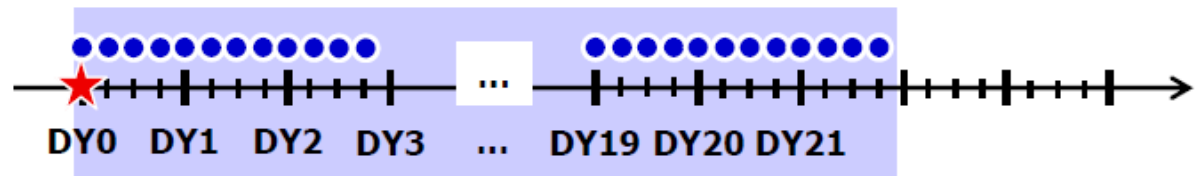
- Simultaneous analysis with a 6-hour assimilation window

- **Experiment2: Analysis from a long (3-week) assimilation window**

- With this long assimilation window, ensemble perturbations of meteorological variables become non-linear so that we do not include wind uncertainty for CO<sub>2</sub> data assimilation (Carbon-Univariate DA)

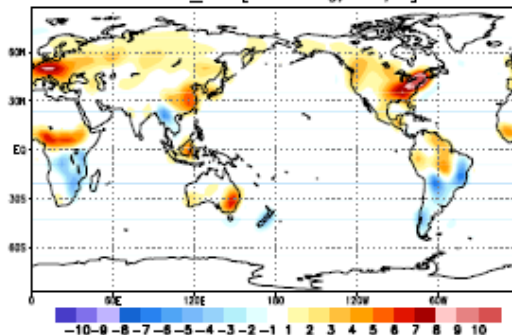
ex. three-week assimilation window

- Observations at every six hours
- ★ Analysis time
- Assimilation window(3 weeks)



### True CO<sub>2</sub> fluxes

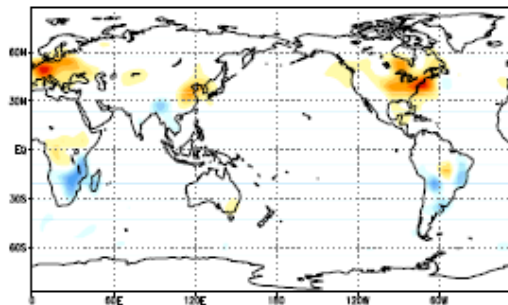
TRUTH\_CF [10<sup>-8</sup>kg/m<sup>2</sup>/s]



▲ After 3 weeks of DA

### Short window [6 hours]

ANAL: LETKF-C @ 00Z22JAN

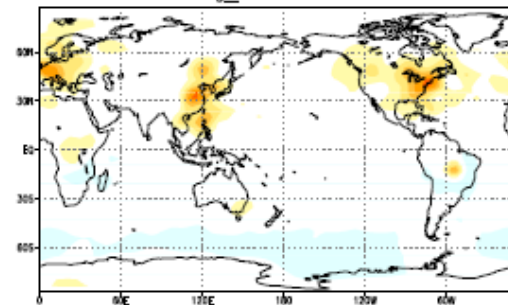


RMSE=1.11e-08

CORR=0.67

### Long window [3 weeks]

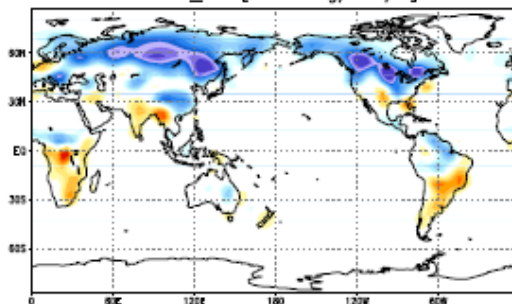
ANAL: Long\_Window @ 00Z22JAN



RMSE=1.24e-08

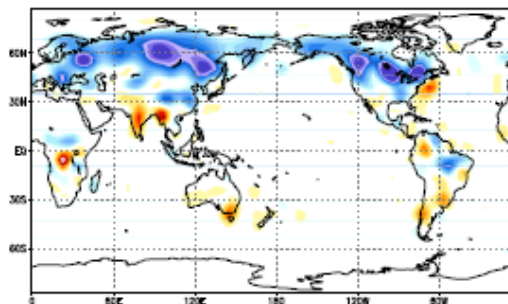
CORR=0.53

TRUTH\_CF [10<sup>-8</sup>kg/m<sup>2</sup>/s]



▲ After 7 months of DA

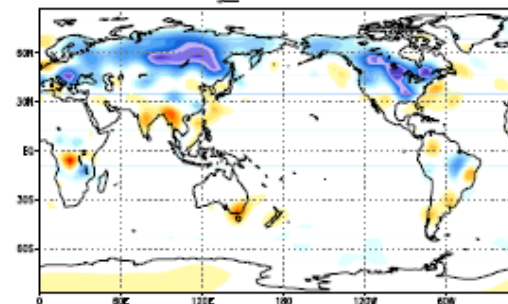
ANAL: LETKF-C @ 00Z30JUL



RMSE=1.12e-08

CORR=0.85

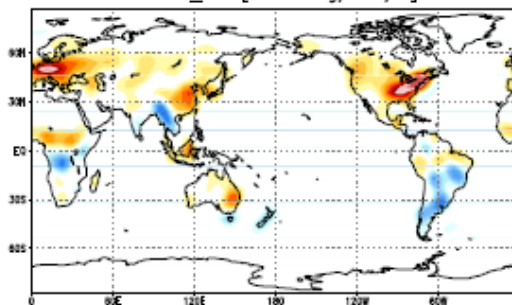
ANAL: Long\_Window @ 00Z30JUL



RMSE=1.17e-08

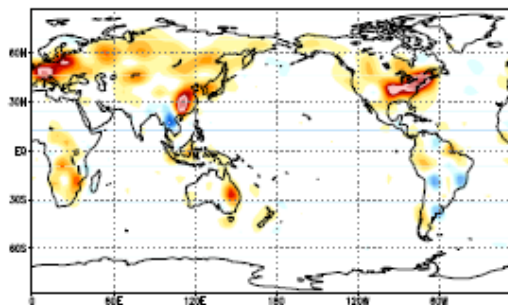
CORR=0.82

TRUTH\_CF [10<sup>-8</sup>kg/m<sup>2</sup>/s]



▲ After ~1 year of DA

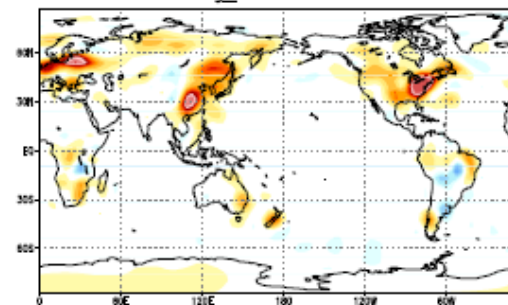
ANAL: LETKF-C @ 00Z24DEC



RMSE=1.25e-08

CORR=0.64

ANAL: Long\_Window @ 00Z24DEC



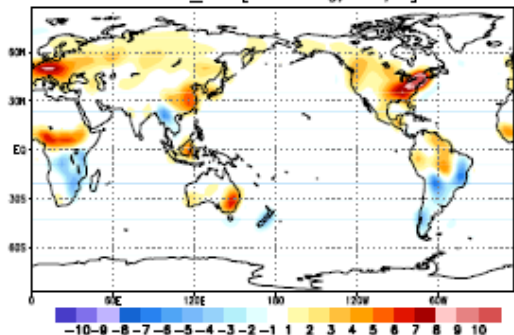
RMSE=1.38e-08

CORR=0.54



### True CO<sub>2</sub> fluxes

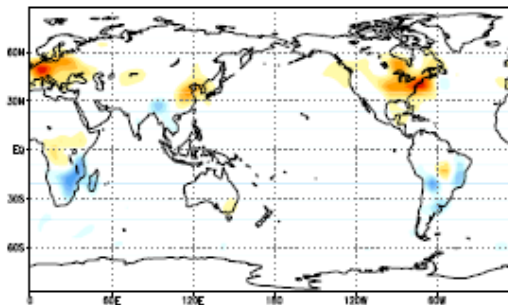
TRUTH\_CF [10<sup>-8</sup>kg/m<sup>2</sup>/s]



▲ After 3 weeks of DA

### Short window [6 hours]

ANAL: LETKF-C @ 00Z22JAN

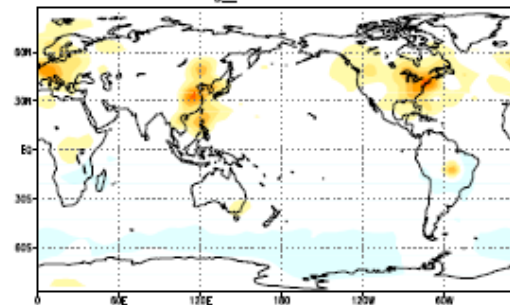


RMSE=1.11e-08

CORR=0.67

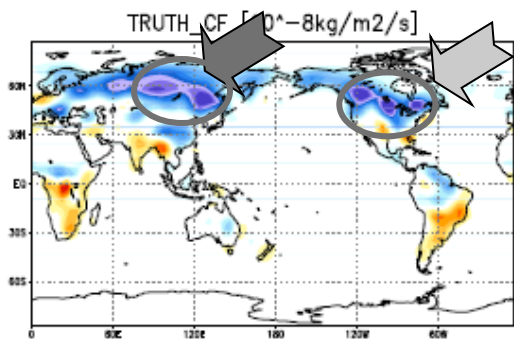
### Long window [3 weeks]

ANAL: Long\_Window @ 00Z22JAN

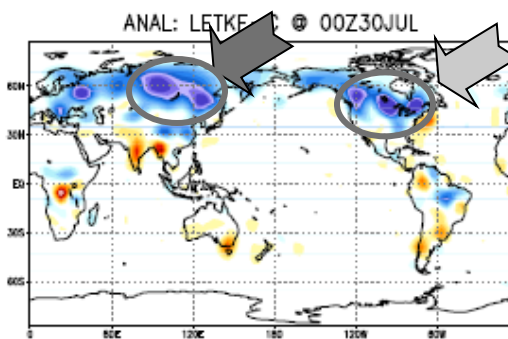


RMSE=1.24e-08

CORR=0.53

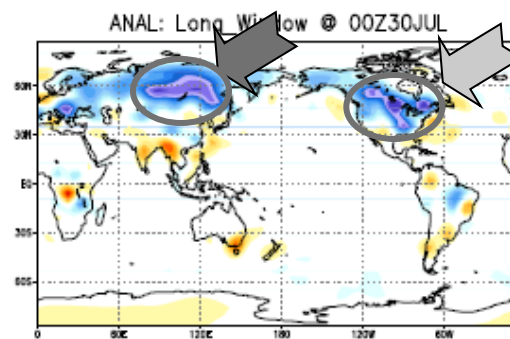


▲ After 7 months of DA



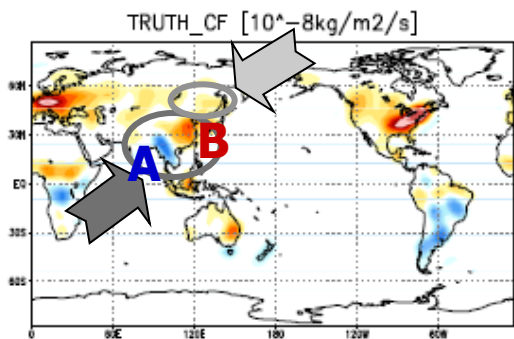
RMSE=1.12e-08

CORR=0.85

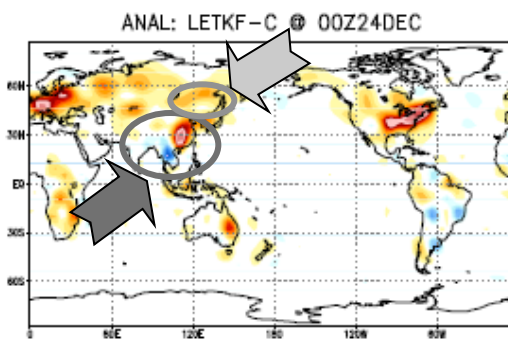


RMSE=1.17e-08

CORR=0.82

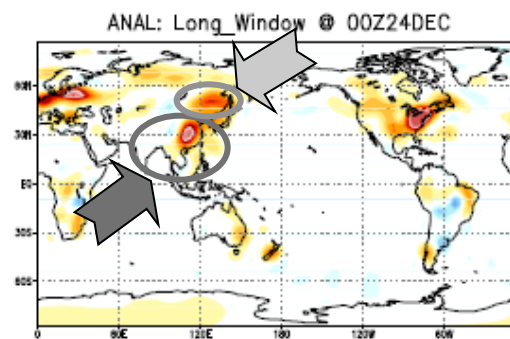


▲ After ~1 year of DA



RMSE=1.25e-08

CORR=0.64



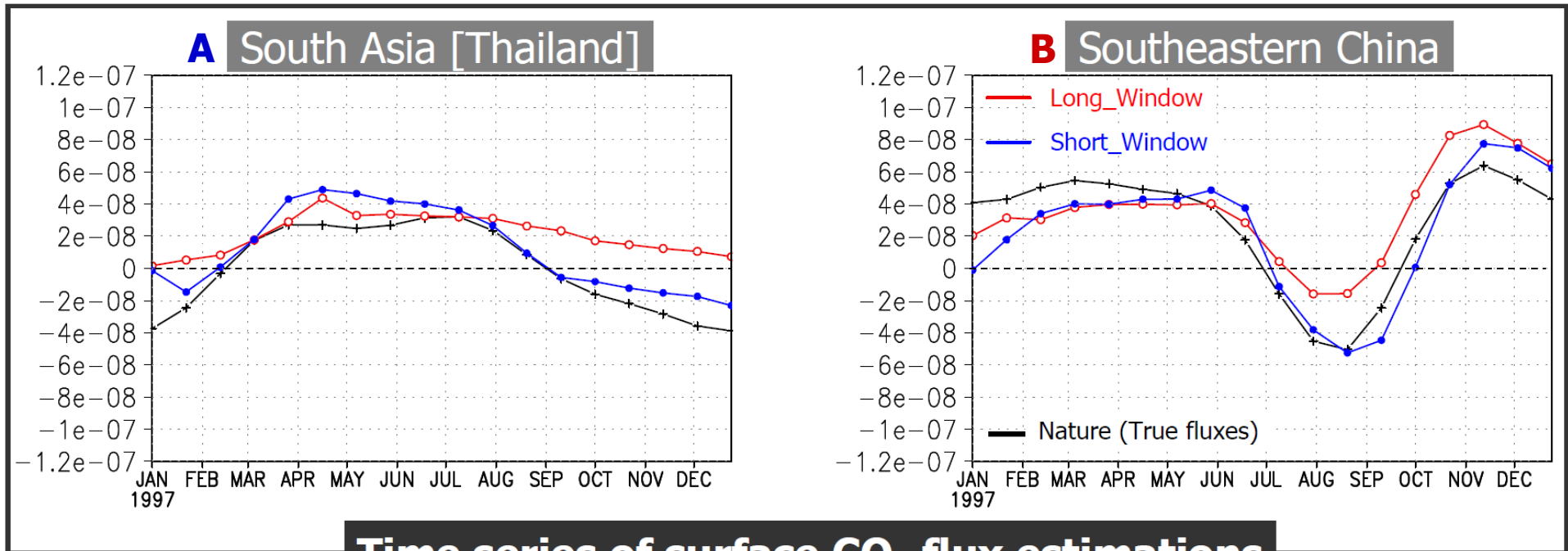
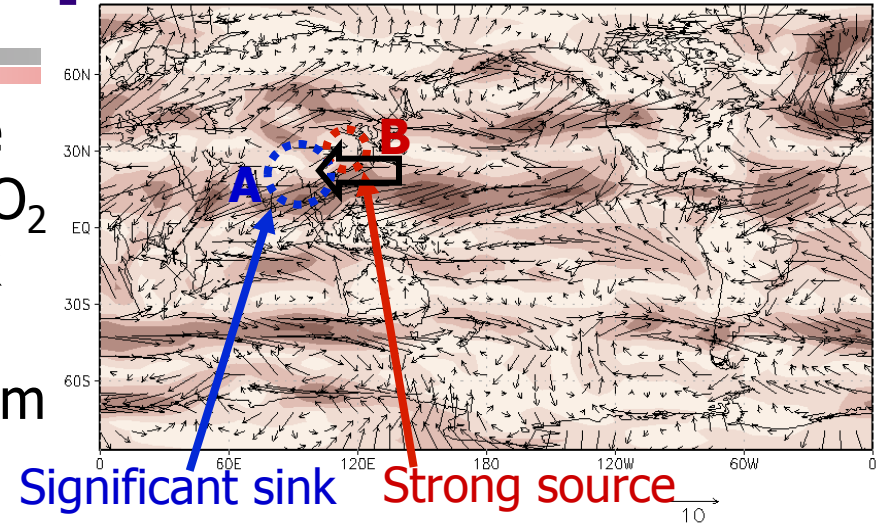
RMSE=1.38e-08

CORR=0.54

# Impact of CO<sub>2</sub> transport

Wind @ month=12

- # **Strong easterly** from the source region to the sink region brings CO<sub>2</sub> increase information over the sink area
- There are incorrect positive CF from OCT to DEC (the end of DA)



**Time series of surface CO<sub>2</sub> flux estimations**

# Summary of LETKF-C carbon fluxes

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- **Assimilation window**

- EnKF has better performance with a short window
- CO<sub>2</sub> observations may be able to provide some information to distant CF, but it becomes blurred.

- **On-going project**

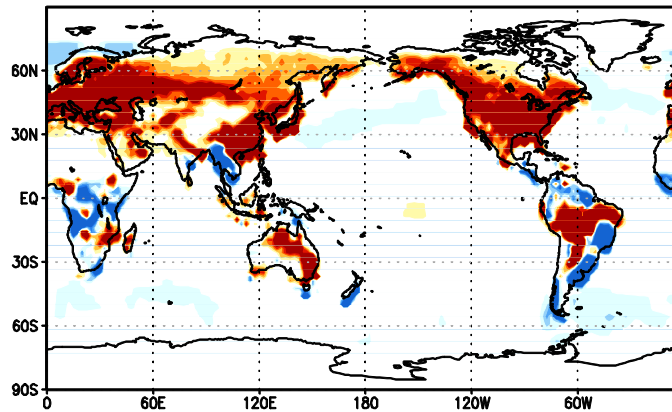
- Implement LETKF-C on the NCAR CAM model
  - OSSE with realistic observations
  - Very slow (26 days)
  - Preliminary results are encouraging
-

# LETKF-C with NCAR CAM3.5

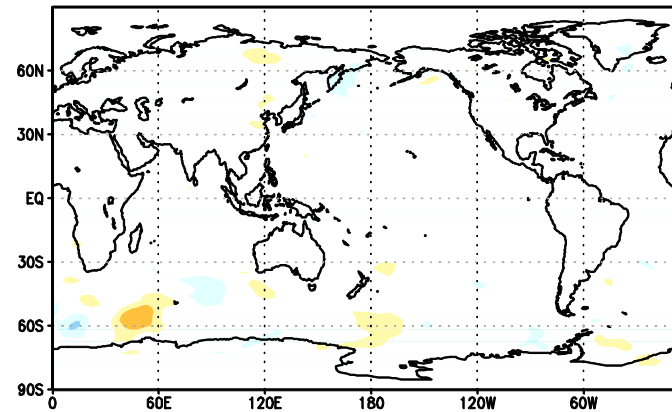
- Model: **CAM 3.5**
  - Finite Volume dynamical core
  - $2.5^\circ \times 1.9^\circ$  of horizontal resolution with 26 layers in the vertical
  - C (atmospheric CO<sub>2</sub>) is an inert tracer
  - Persistence forecast of CF
- Simulated observations with **real observation coverage**
  - Conventional data for U, V, T, q, Ps
  - Ground-based observations of atmospheric CO<sub>2</sub>
    - ✓ ~10 hourly and ~100 weekly records on the globe
  - Remote sensing data of column mixing CO<sub>2</sub>
    - ✓ **AIRS** whose averaging kernel peaks at mid-troposphere
- Initial conditions: random (*no a-priori* information)
- 64 ensembles

# LETKF-CAM3.5 CF analysis

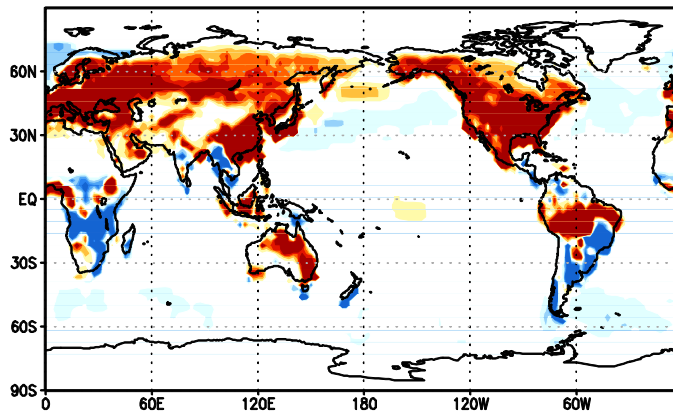
True CF @ initial time (00Z01JAN)



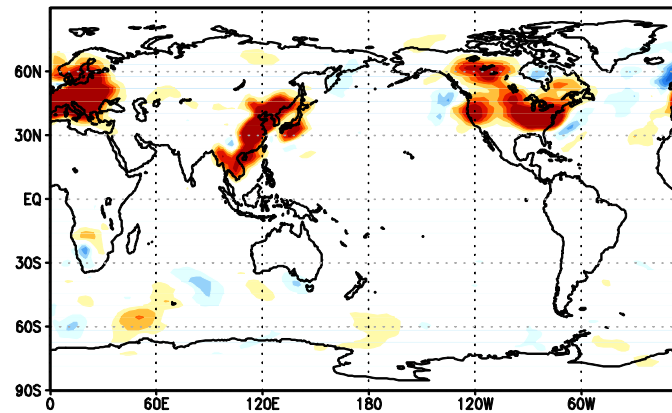
Initial CF



True CF @ 00Z27JAN



CF analysis @ 00Z27JAN

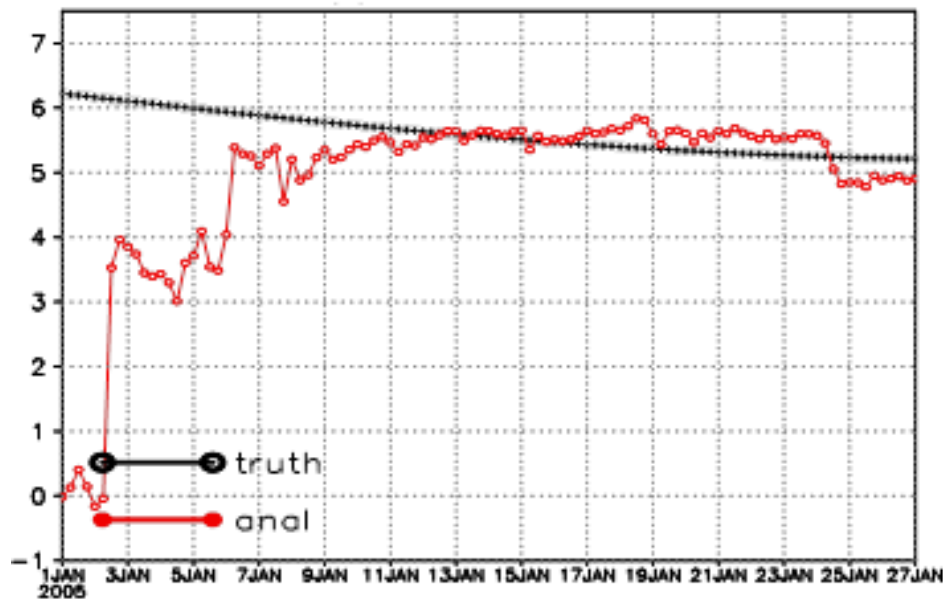


-2 -1.6 -1.2 -0.8 -0.4 0.4 0.8 1.2 1.6 2  $10^{-8} \text{kgCO}_2/\text{m}^2/\text{s}$

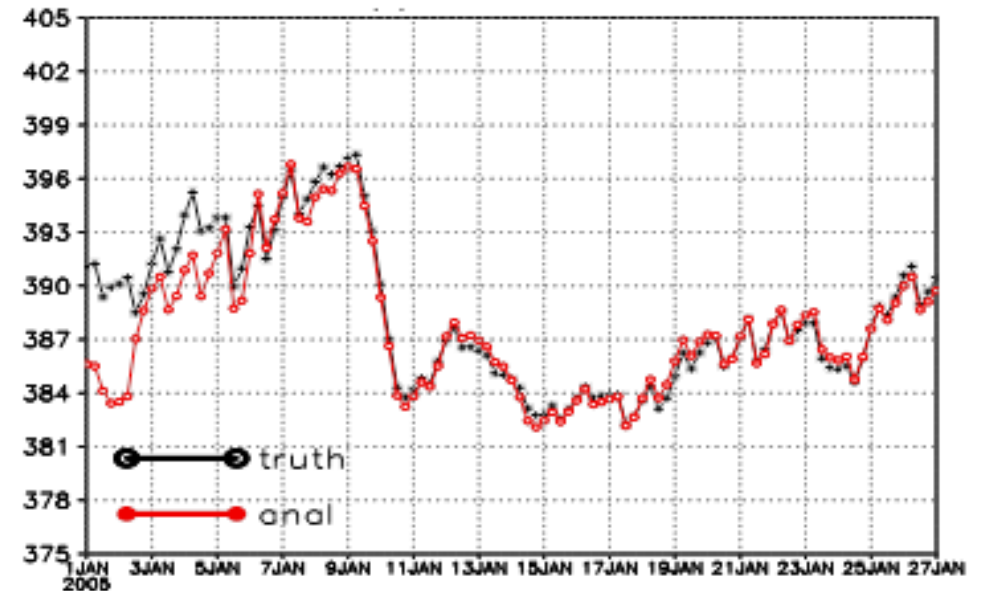
# LETKF-CAM3.5 CF analysis

- Time series of surface CO<sub>2</sub> fluxes and atmospheric CO<sub>2</sub> concentrations over Europe (observation-rich area)

(a) Surface CO<sub>2</sub> fluxes over EUR



(b) Atmospheric CO<sub>2</sub> over EUR

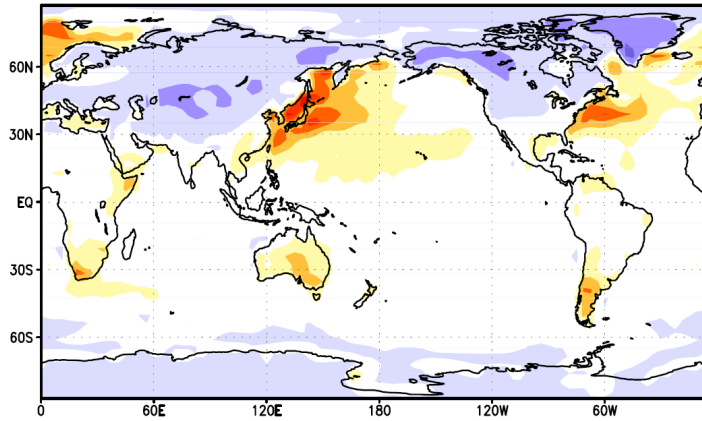


# Surface Heat and Moisture Fluxes

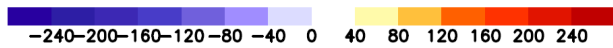
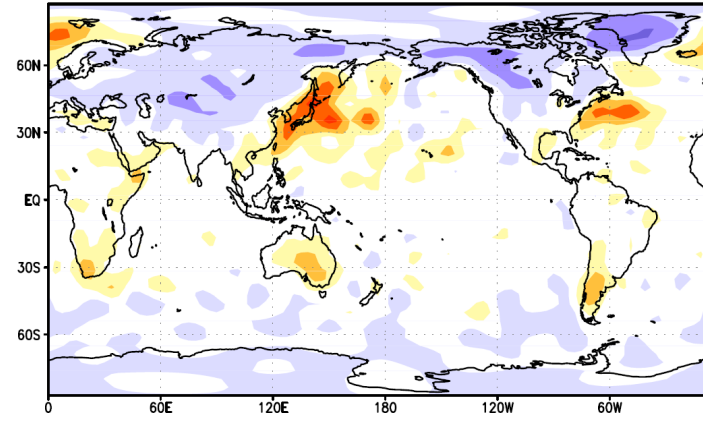
- Can we estimate **surface moisture/heat fluxes** by assimilating atmospheric moisture/temperature observations? *We can use the same methodology!*
- OSSEs
  - Nature: SPEEDY (perfect model)
  - Forecast model: SPEEDY with persistence forecast of Sensible/Latent heat fluxes (SHF/LHF)
  - Observations: conventional observations of (U, V, T, q, Ps) and AIRS retrievals of (T, q)
  - Analysis: U, V, T, q, Ps + SHF & LHF
- Fully multivariate data assimilation
- Adaptive multiplicative inflation + additive inflation
- Initial conditions: random (*no a-priori information*)

# Results: SHF (perfect wind stress model)

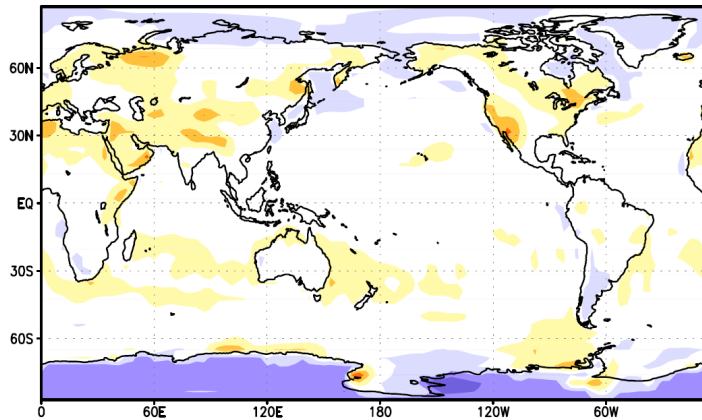
**True SHF @ end of JAN**



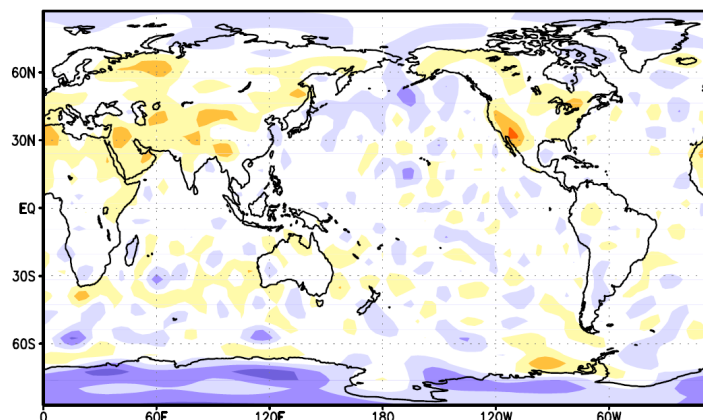
**SHF analysis @ end of JAN**



**True SHF @ end of JUN**



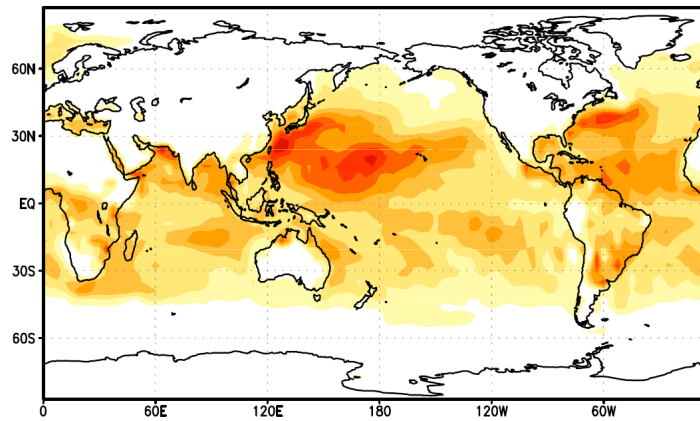
**SHF analysis @ end of JUN**



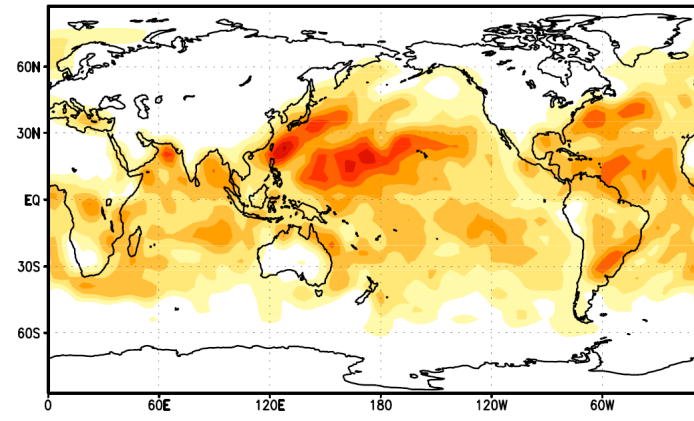


# Results: LHF (perfect wind stress model)

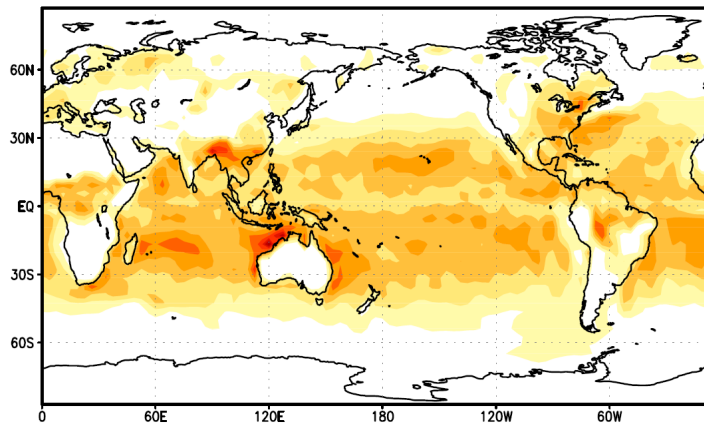
**True SHF @ end of JAN**



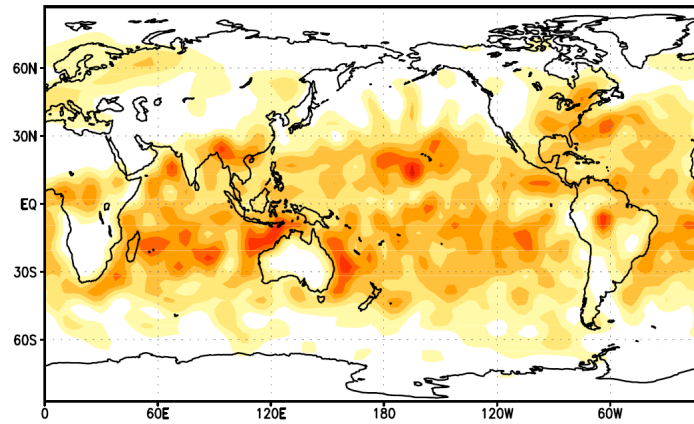
**SHF analysis @ end of JAN**



**True SHF @ end of JUN**

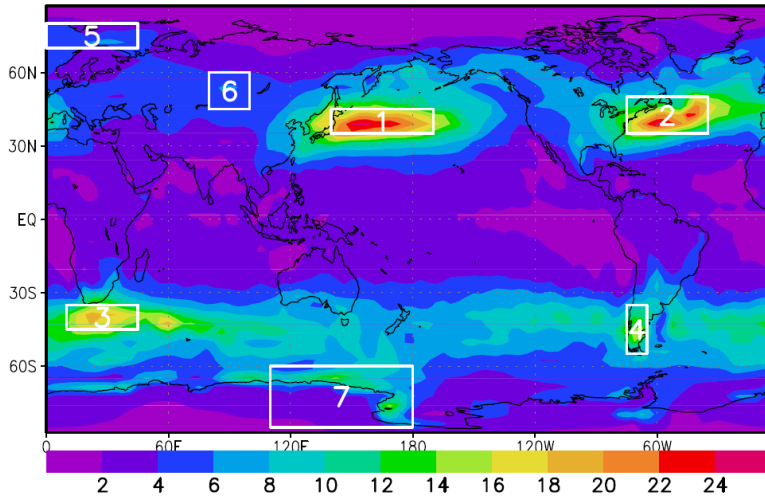


**SHF analysis @ end of JUN**



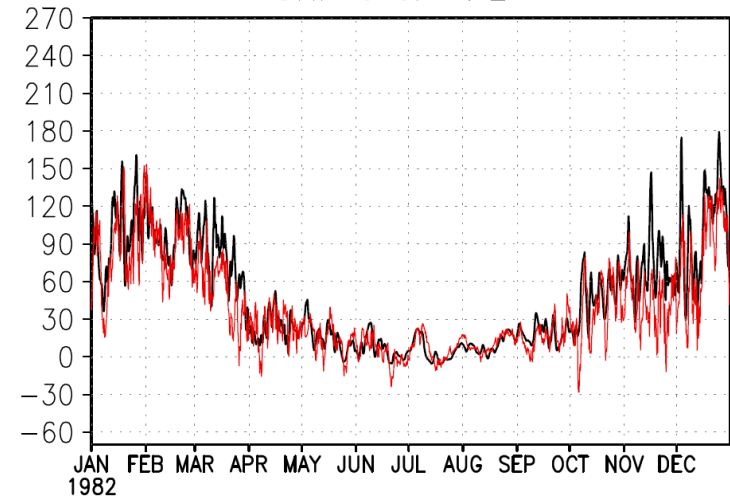
# Time series of SHF (perfect WSTR model)

1yr mean of dSHF(6hr)

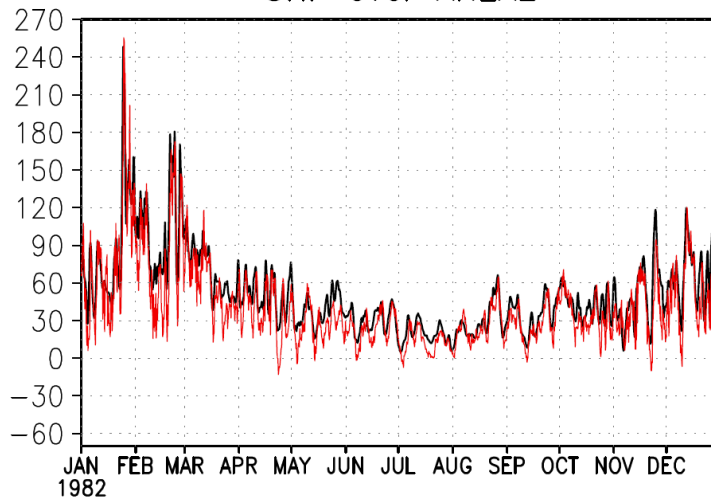


BLACK:NATURE

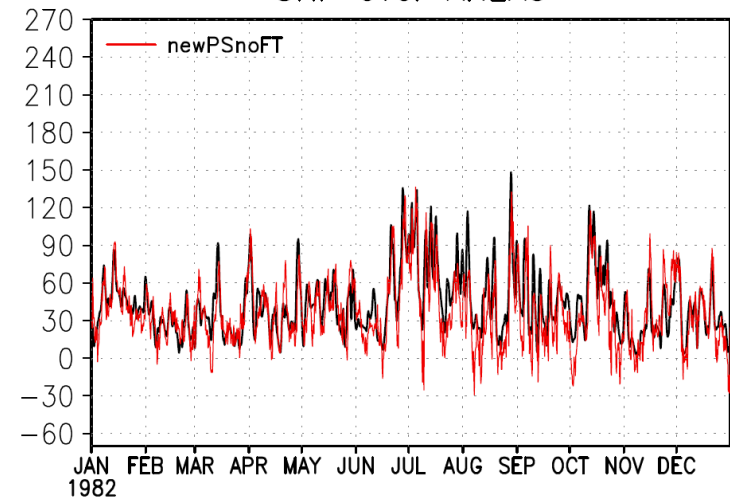
SHF over AREA1



SHF over AREA2

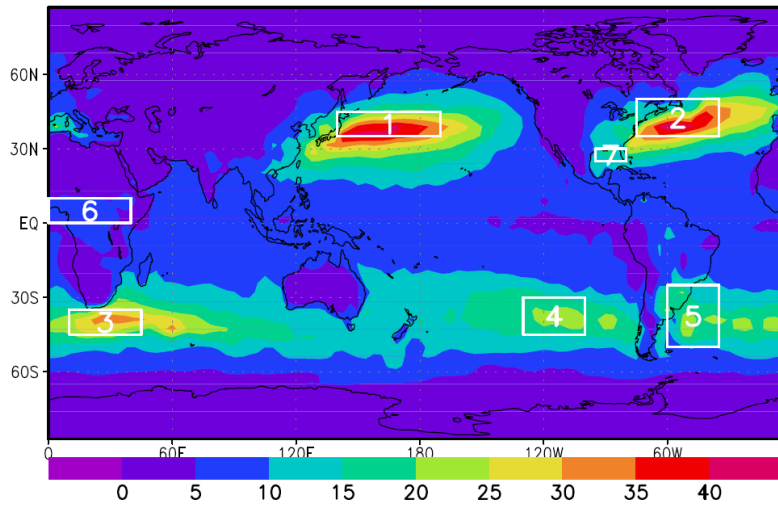


SHF over AREA3



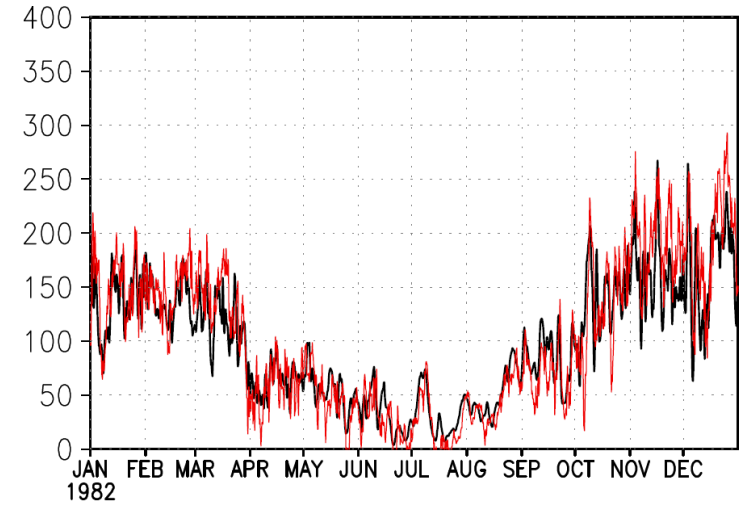
# Time series of LHF (perfect WSTR model)

1yr mean of dLHF(6hr)

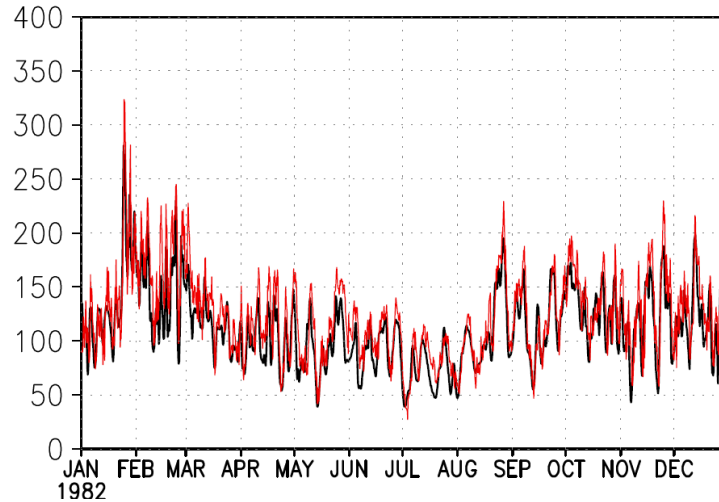


BLACK:NATURE

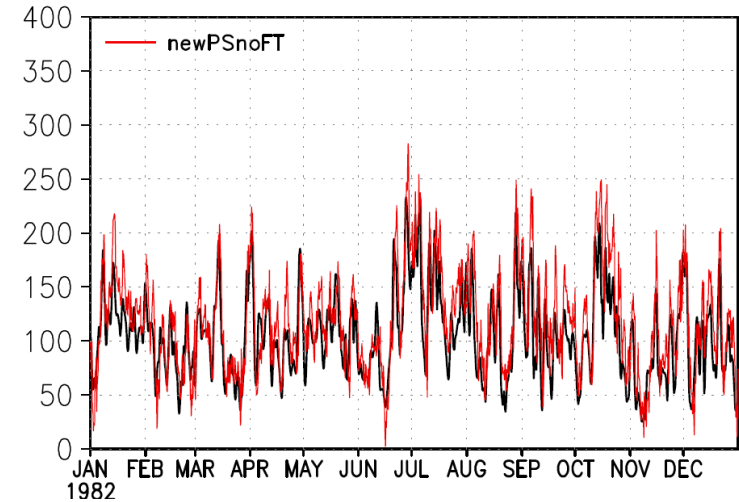
LHF over AREA1



LHF over AREA2



LHF over AREA3



# Summary of SHF & LHF DA (perfect WSTR model)

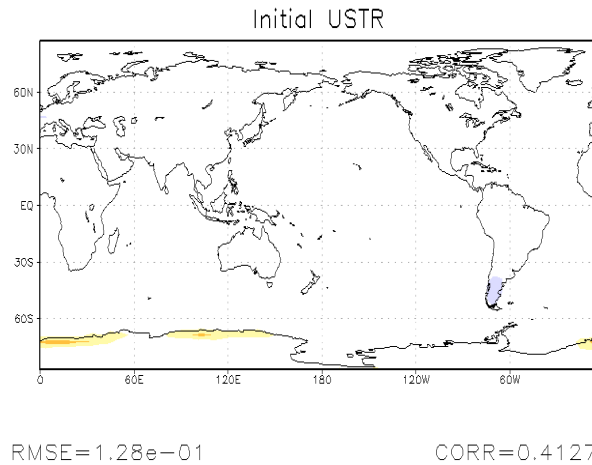
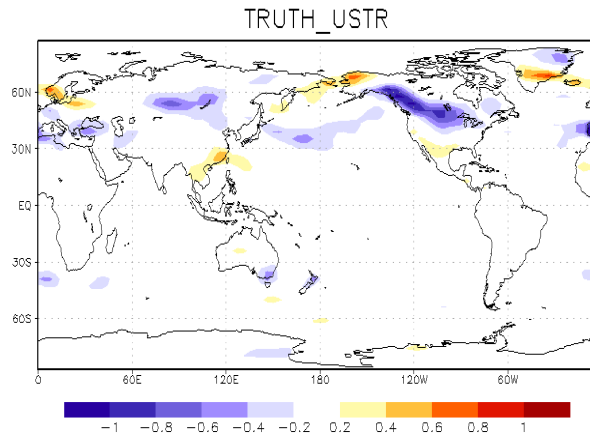
---

- AIRS retrieval data of T and q provide very accurate and abundant information for constraining surface heat and moisture fluxes
    - Observation error: 1K for T and 1.0g/kg for q
    - Global coverage at every 12 hours
  - ➔ After a short spin-up period (~a week), **estimation of SHF and LHF converges very well**
  - Results shown here are given under the assumption of perfect wind stress model. We should test this system in presence of model errors in the future.
-

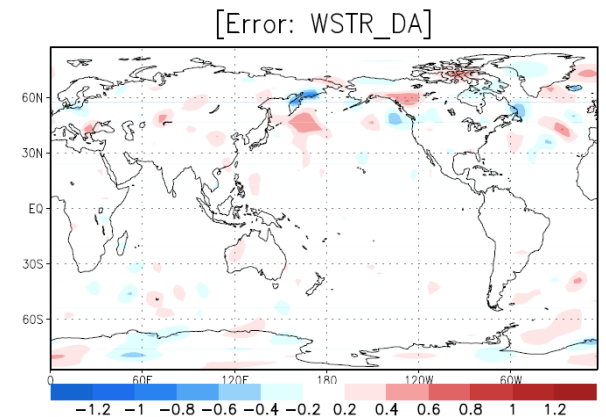
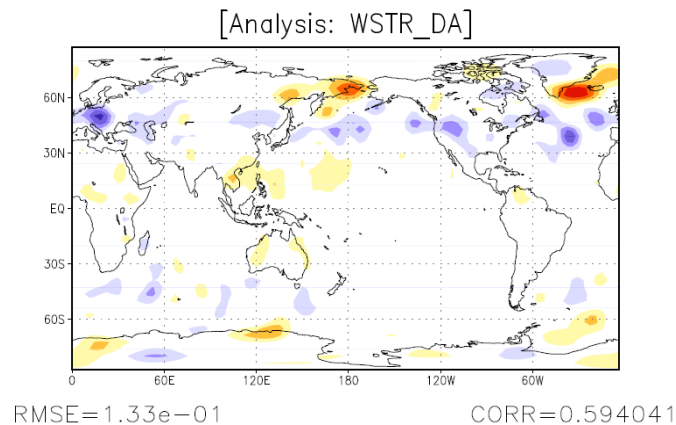
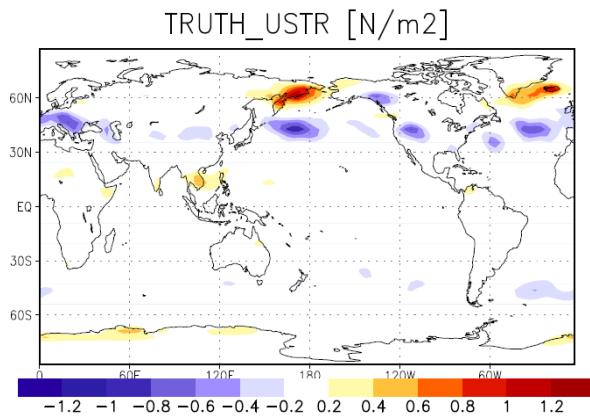
# Can we also estimate wind stress?

- OSSEs
  - Nature: SPEEDY
  - Forecast model: SPEEDY with persistence forecast of Sensible/Latent heat fluxes (SHF/LHF) and wind stress (USTR, VSTR) **[ALL\_FLUXES]**
  - Observations: conventional observations of (U, V, T, q, Ps), AIRS retrievals of (T, q), **and ASCAT ocean surface wind observations**
    - ✓ **Observation error of ASCAT: 3.5m/s (not as good as AIRS data)**
    - ✓ ASCAT covers the global ocean every 12 hours, but little overlapped with AIRS data distribution
  - Analysis: U, V, T, q, Ps + **SHF, LHF, USTR, VSTR**
- Fully multivariate data assimilation
- Initial conditions: random (*no a-priori information*)

# Result: USTR from [ALL\_FLUXES]



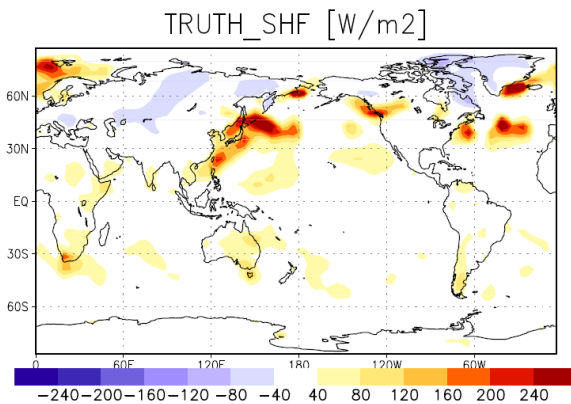
← Initial condition includes **no a-priori** information of USTR



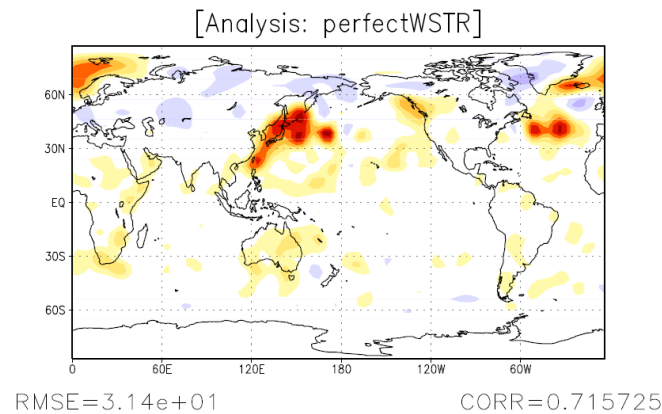
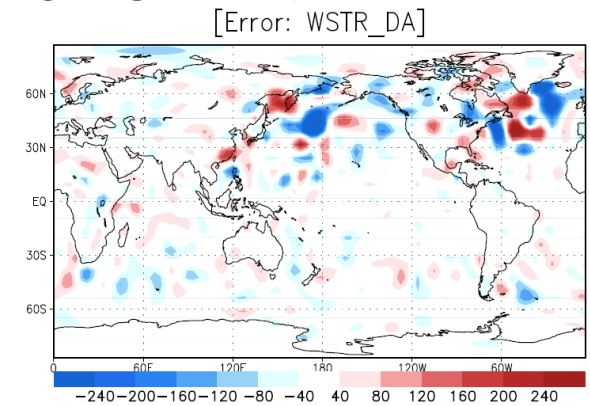
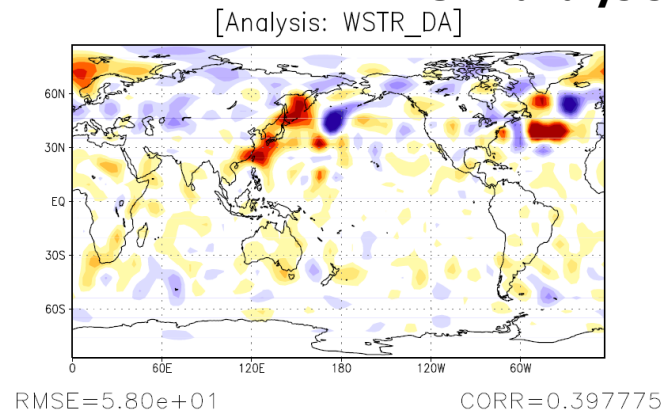
↑ After one month of DA, USTR estimation is close to the true USTR

# Results: SHF from [ALL\_FLUXES]

## ▼ SHF analysis with WSTR DA ▼



▲ True SHF

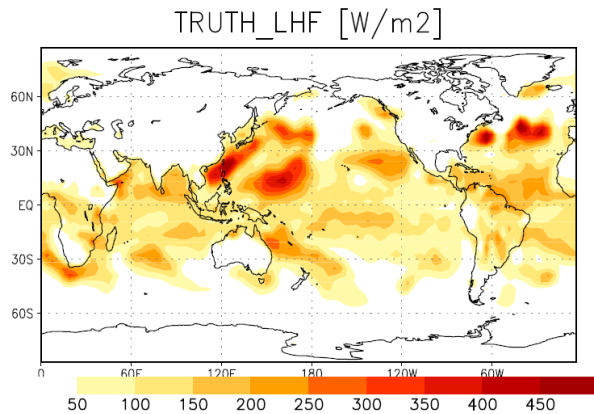


▲ SHF analysis with perfect WSTR ▲

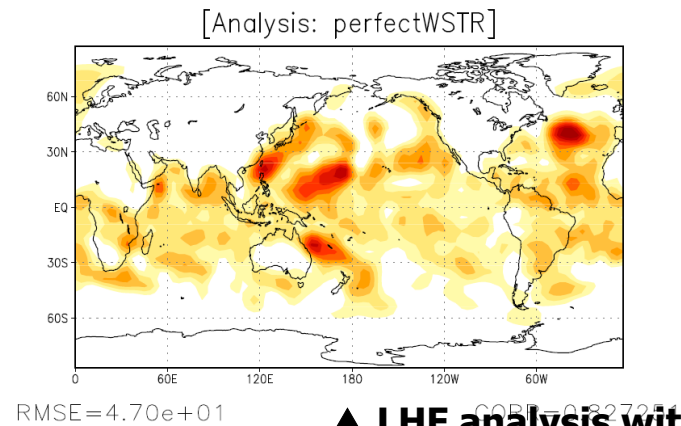
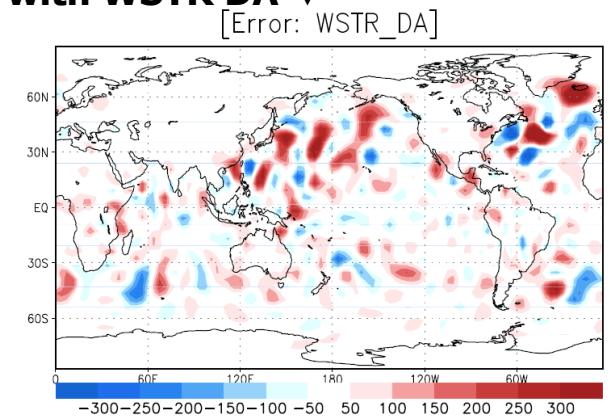
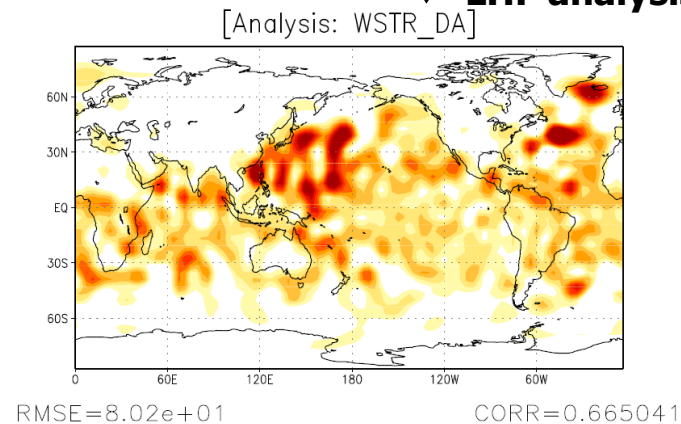
- Although the estimated wind stress does look okay, the **imperfection of the wind stress contaminates the estimation of SHF and LHF significantly**

# Results: LHF from [ALL\_FLUXES]

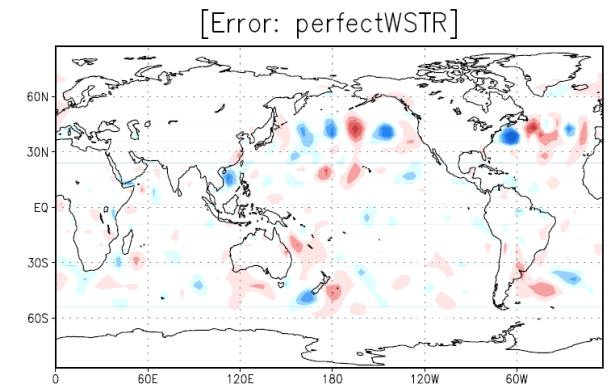
## ▼ LHF analysis with WSTR DA ▼



▲ True LHF



▲ LHF analysis with perfect WSTR ▲



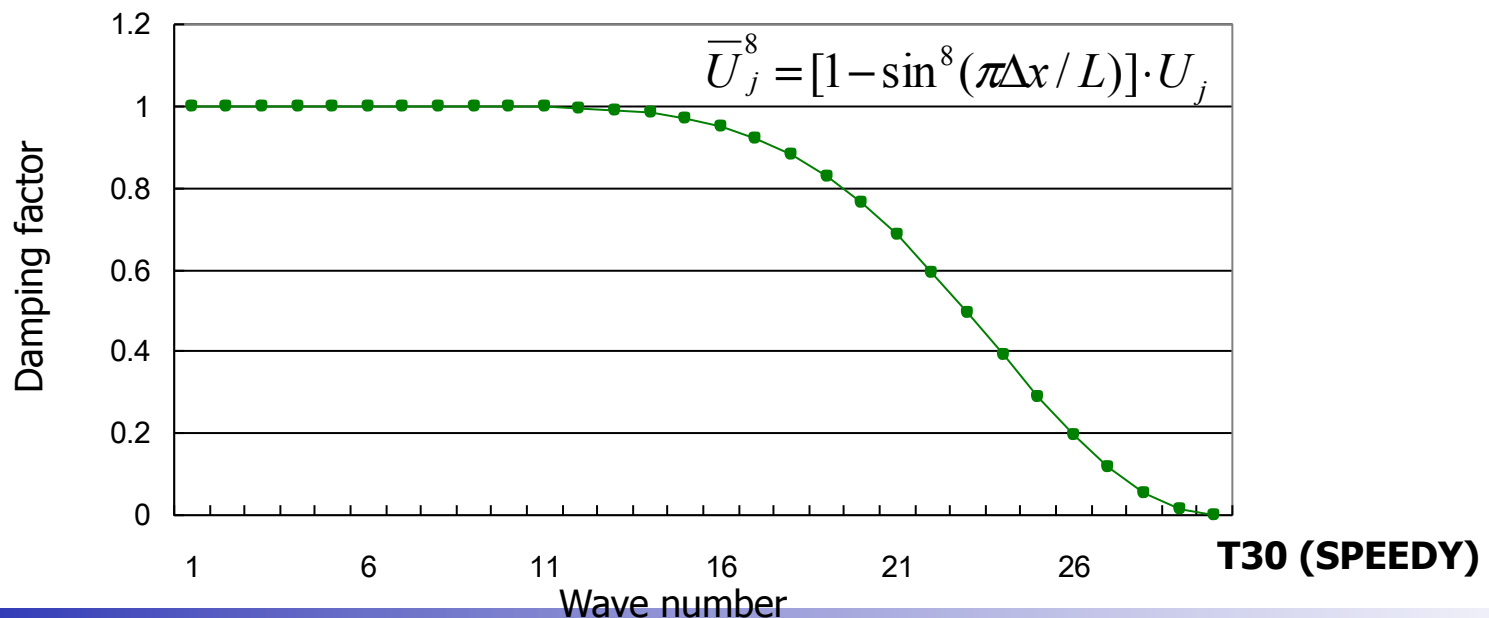
- Although the estimated wind stress does look okay, the **imperfection of the wind stress contaminates the estimation of SHF and LHF significantly**

→ **Analysis diverged...**



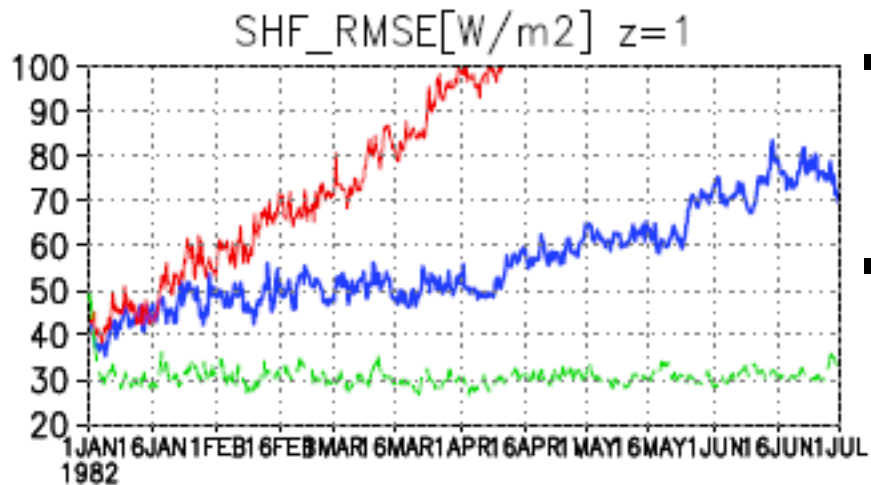
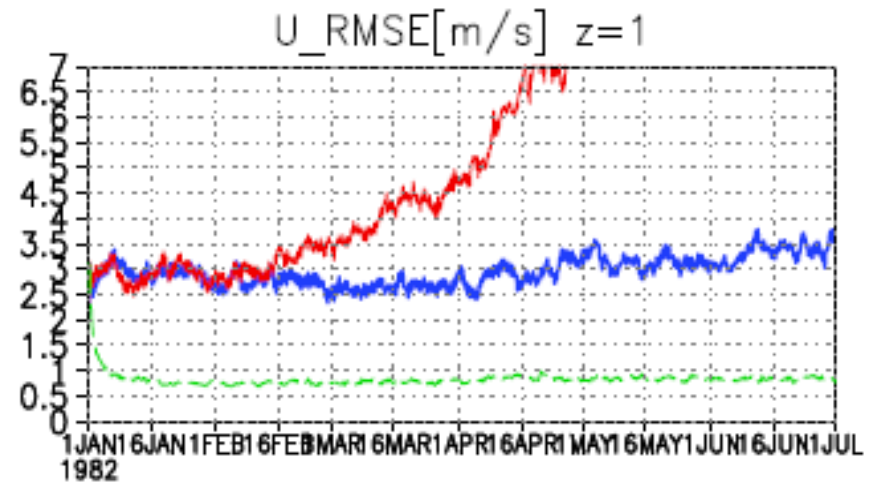
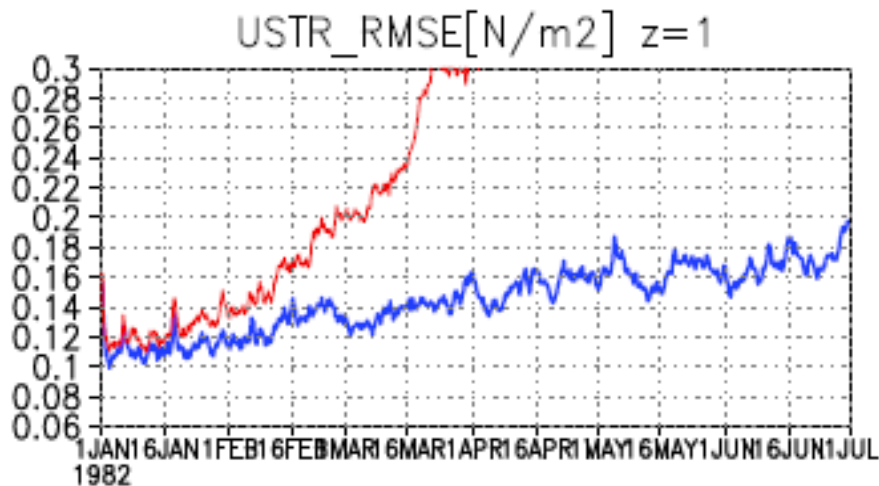
# 1) Filtering analysis increments?

- Due to the **limited observational contents**, we may not be able to expect analysis increment with a full resolution
  - Filtering out high wavenumbers from the analysis increments for 2d parameters (SHF, LHF, USTR, VSTR) using the Shapiro filter (Kalnay, 2003)



# Time series of RMS errors

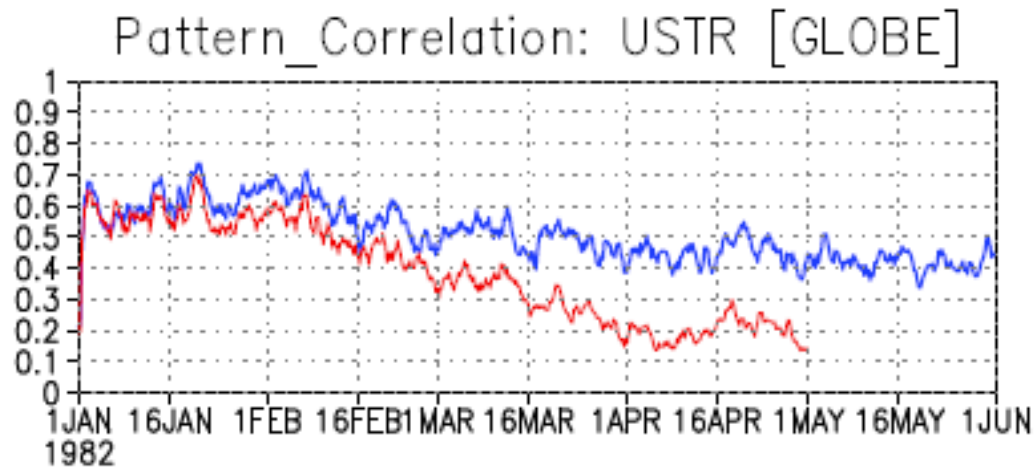
— Analysis w/o filtering — Analysis w/ filtering — Analysis with perfect WSTR



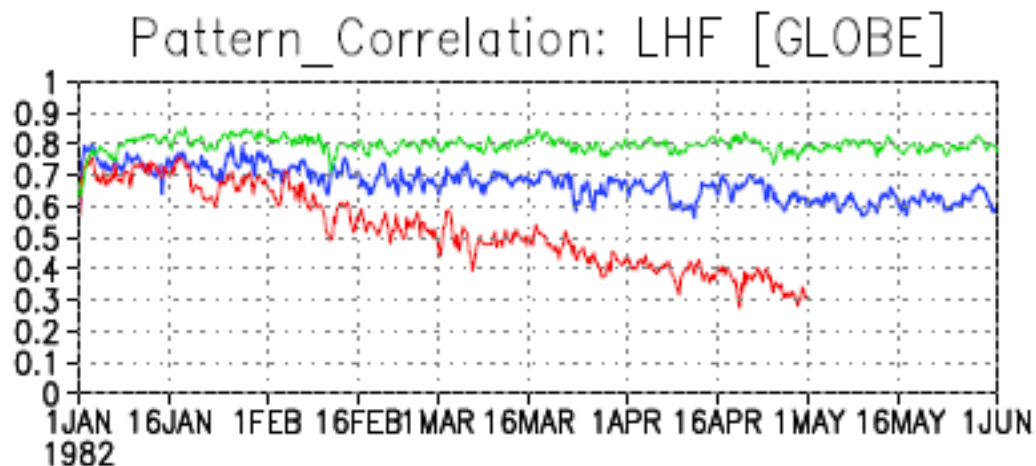
- Filtering analysis increment reduces analysis error remarkably and produces quite stable results
- However, there are still errors growing in time especially for the parameters (SHF, LHF, USTR, VSTR)

# Time series of spatial correlation

— Analysis w/o filtering    — Analysis w/ filtering    — Analysis with perfect WSTR



- Filtering analysis increments prevents (or delays) the estimated parameters from losing spatial correlation in time.



## 2) increasing ensemble size

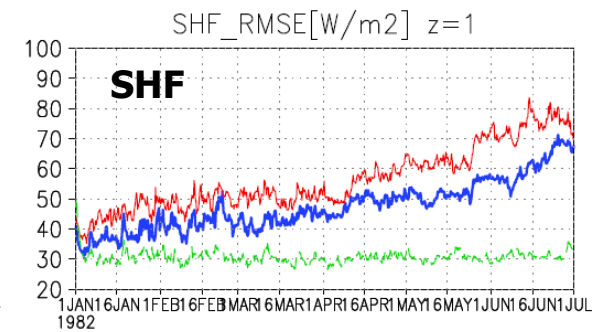
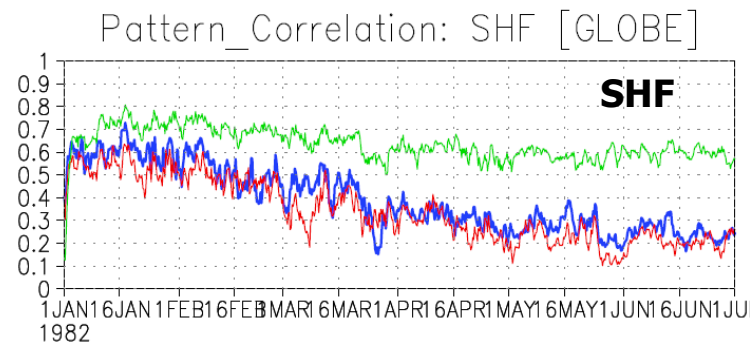
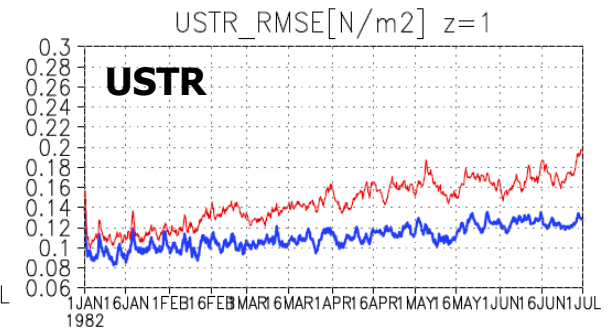
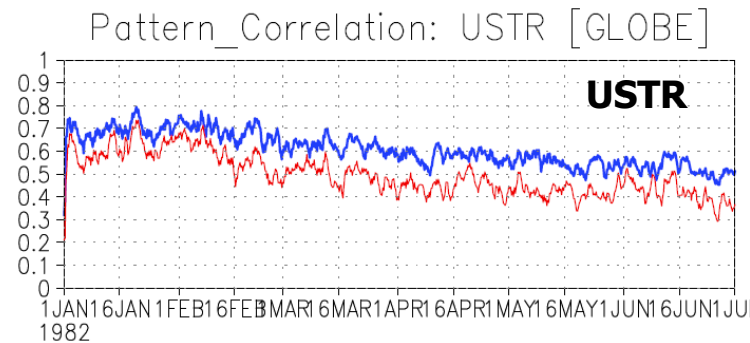
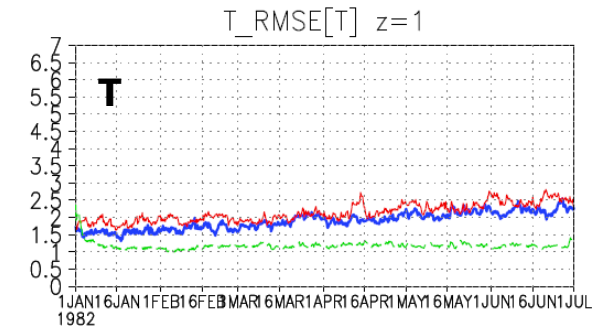
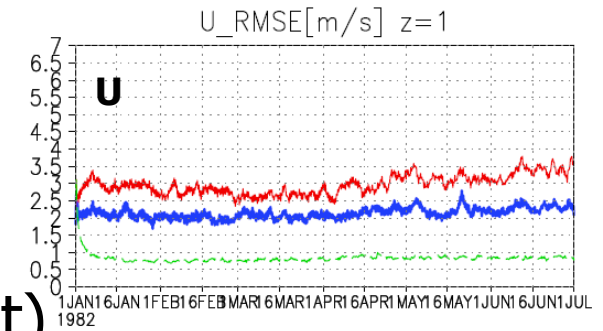
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- We introduce **too many unknowns** into the analysis system, and thus **increasing ensemble size** may help.
  - Control experiments: **40** ensembles
  - Experiments with **80** ensembles have been examined
-

# Results

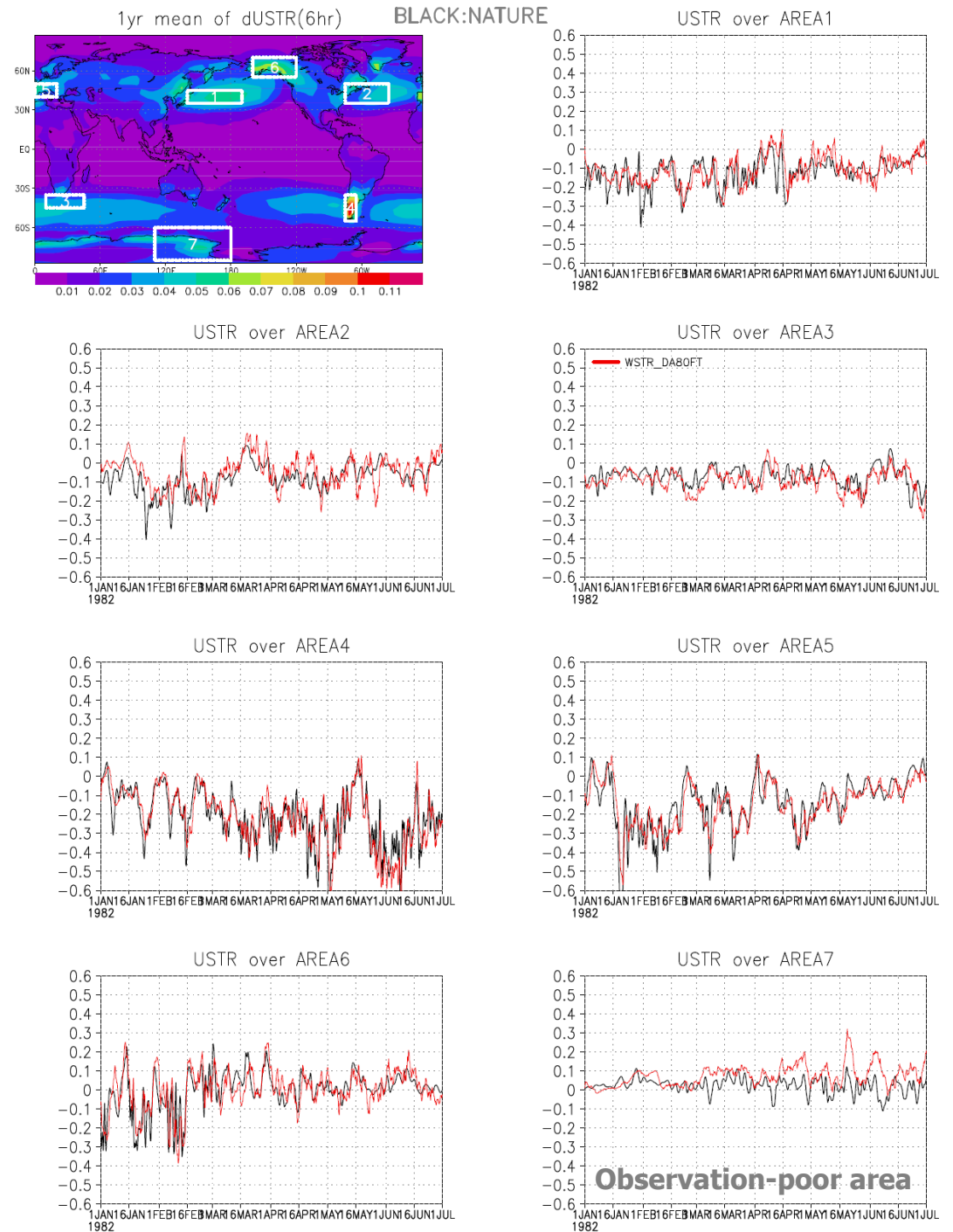
- Spatial correlation (left) and RMSE (right)
  - Blue: 80 ensembles
  - Red: 40 ensembles
  - Green: perfect WSTR with 40 ensembles

→ Doubling ensemble size reduces error and increase spatial correlation of the estimates, but it seems not enough to produce stable estimation of parameters throughout the analysis period



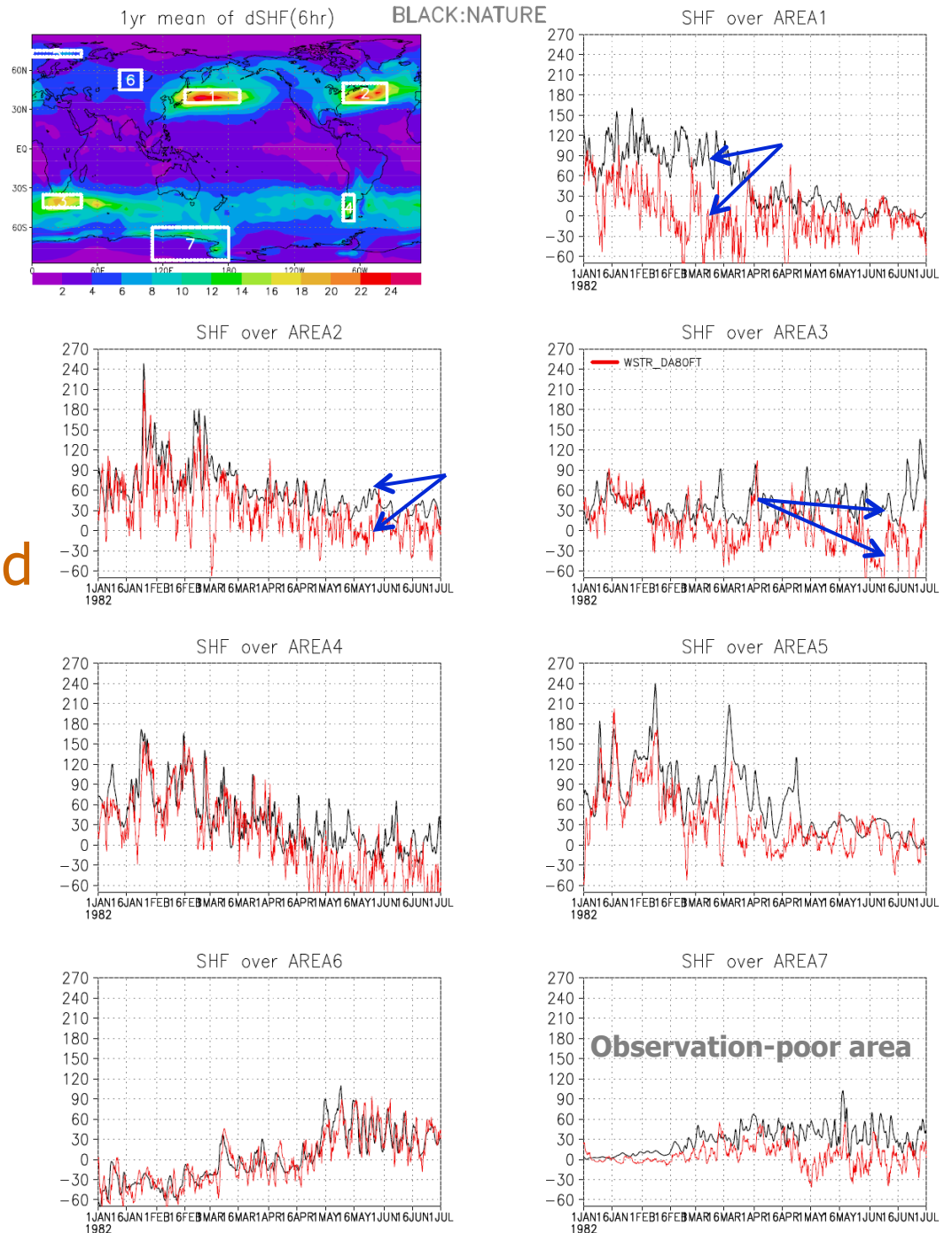
# USTR

- Estimated USTR looks reasonable



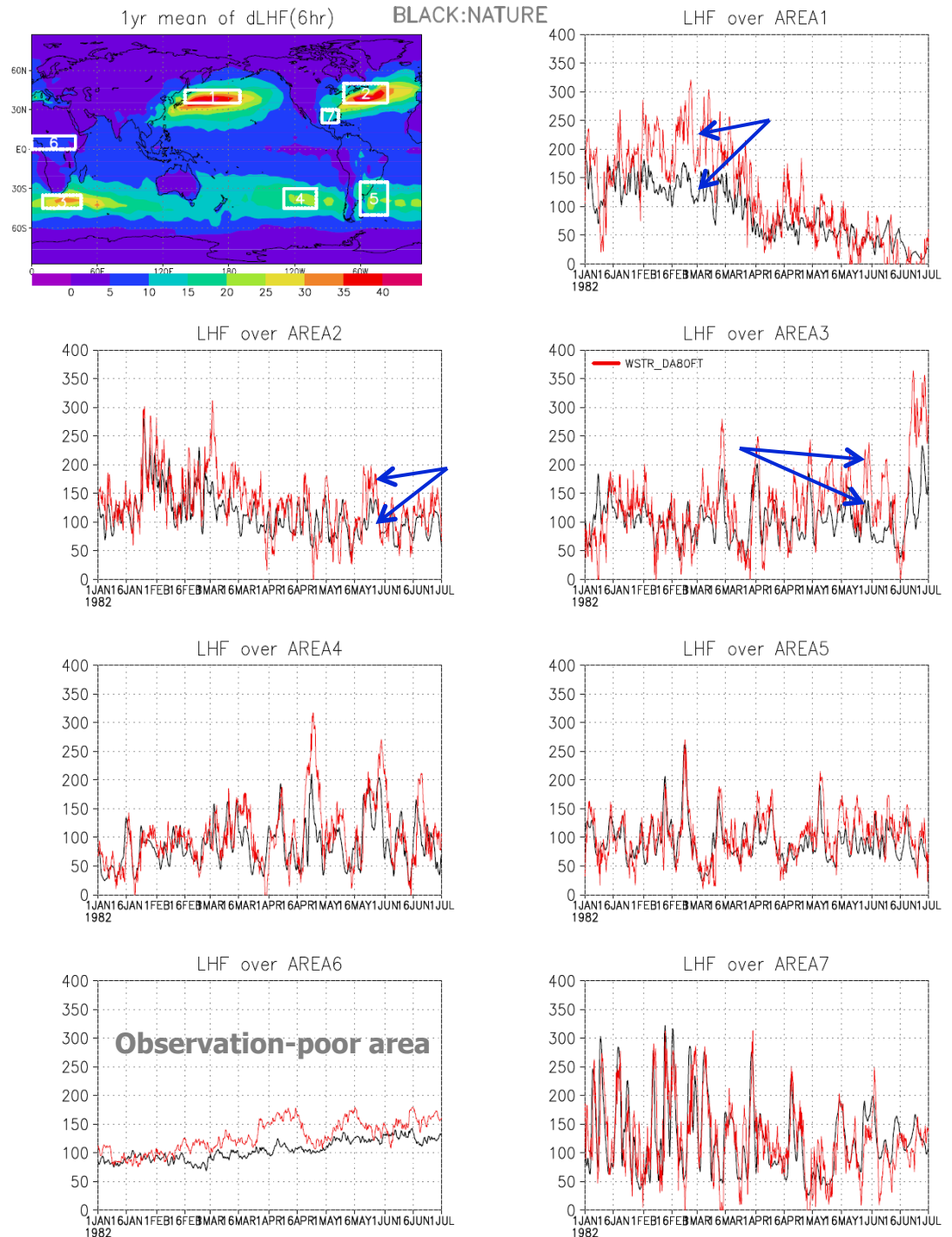
# SHF

- SHF tends to be **underestimated**, especially over the ocean
- Estimation **over the land** (area 4 and 6) has **relatively good** performance
  - Better observations over land



# LHF

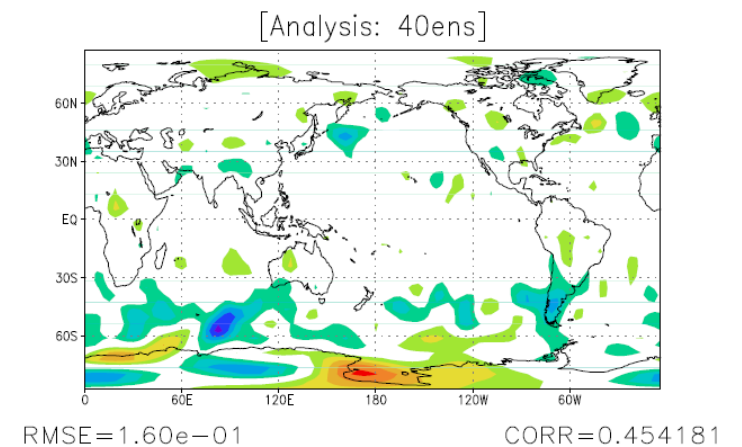
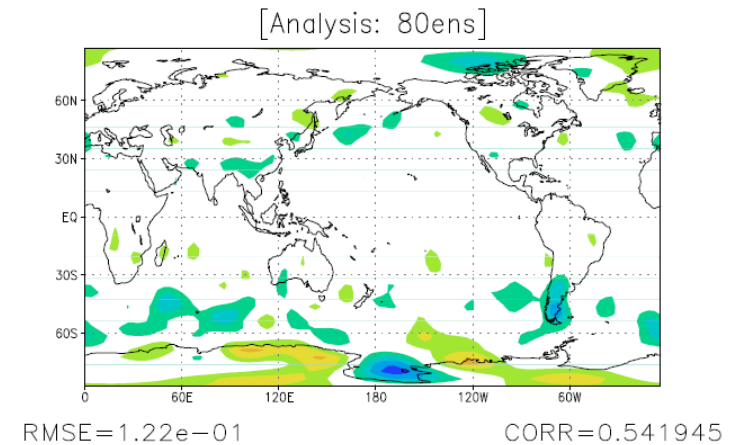
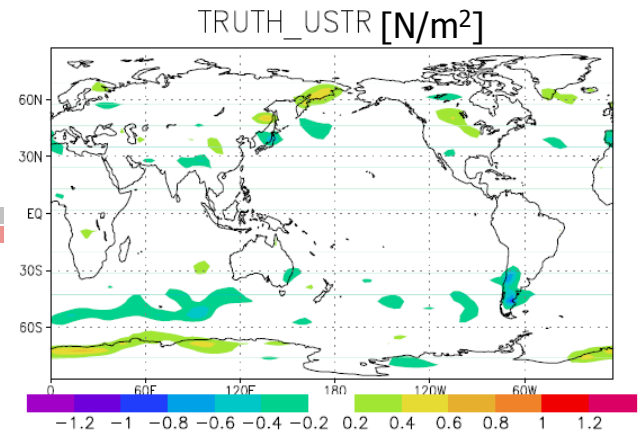
- LHF is **overestimated**, especially over the ocean
  - ➔ “*improper partitioning*” (e.g. *Vinukollu et al. 2012*)
- Estimation **over the land** (area 5 and 7) has **relatively good** performance
  - Area 6 is also over the land, but there are few rawinsonde observations
- ➔ Results depends on the observational contents since our methods does not use any a-priori information





# Global maps of USTR

- 00Z01JUN after a 5-month DA
- Over land, estimation of USTR agrees well with the true USTR in both experiments w/ 80 and 40 ensembles



# Summary for Windstress, SHF, LHF DA

---

- We attempt to estimate wind stress (WSTR) within LETKF (without computing it from a physical parameterization of the perfect model) in addition to SHF/LHF estimation
  - Addition of ASCAT data gives fairly good estimation of WSTR
  - The analysis system still needs further improvement to avoid a negative feedback among WSTR, SHF, LHF, and other prognostic variables due to the imperfect WSTR.
    - ✓ Filtering analysis increment & increasing ensemble size help.

# Ji-Sun Kang's Future Plans

- I'm moving and starting a new career in Korea, January 2013
- KIAPS (Korea Institute of Atmospheric Prediction Systems)
  - A new institution, launched April 2011 as one of the major projects pushed by the Korea Meteorological Administration (KMA)
  - To develop the next generation operational numerical weather prediction model by developing the core technologies.



# Future Plans

- Work at KIAPS
  - Data assimilation team will be **in a research mode** for a while, before physics and dynamics teams will develop an early version of the model
  - **MOU with UMD** will allow me to keep collaborating with you all.



A decorative graphic consisting of a vertical grey line on the left, a horizontal grey line at the top, and a horizontal blue line at the bottom. A red horizontal bar is positioned just below the top grey line. In the top right corner, there are three overlapping circles: a blue one, a grey one, and a red one.

**THANK YOU VERY MUCH!**

# Summary

- We have shown the feasibility of **simultaneous analysis of meteorological and carbon variables within LETKF** framework through the simulation experiments.
- The system LETKF-C has been tested in a intermediate-complexity model SPEEDY-C with excellent results.
  - **Multivariate data assimilation with “localization of the variables”** (Kang et al. 2011)
  - Advanced data assimilation methods for CO<sub>2</sub> flux estimation have been explored (Kang et al. 2012)
- The implementation of the LETKF-C to NCAR CAM 3.5 model is now in progress
  - Analysis step shows very good performance in OSSE with real observation coverage
  - Analysis cycle with a forecast step will be operated soon
- The same methodology has been applied to **estimating surface fluxes of heat, moisture and momentum**, and the results are promising!